



UNIVERSITY  
OF LJUBLJANA

**FMF**

Faculty of Mathematics  
and Physics



# From Polygonal Bounces to FindBounce

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Joint Yonsei-Konkuk-Sogang

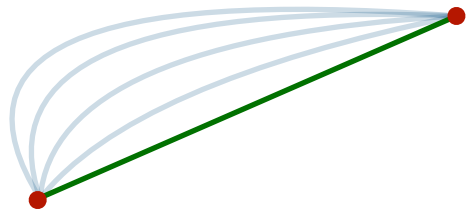
Mini-workshop on FOPT

Miha Nemevšek, 6 February 2025

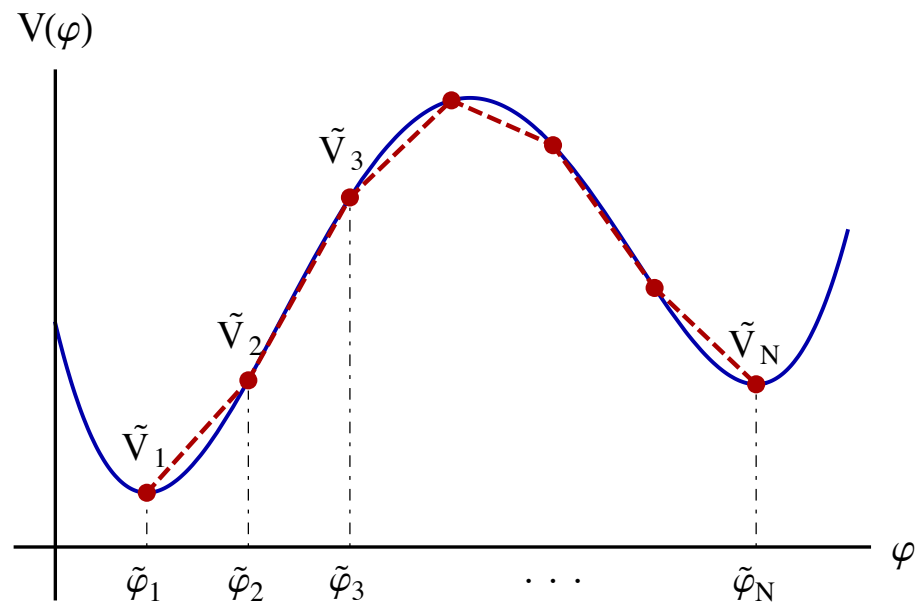


Slovenian Research and Innovation Agency

# Outline

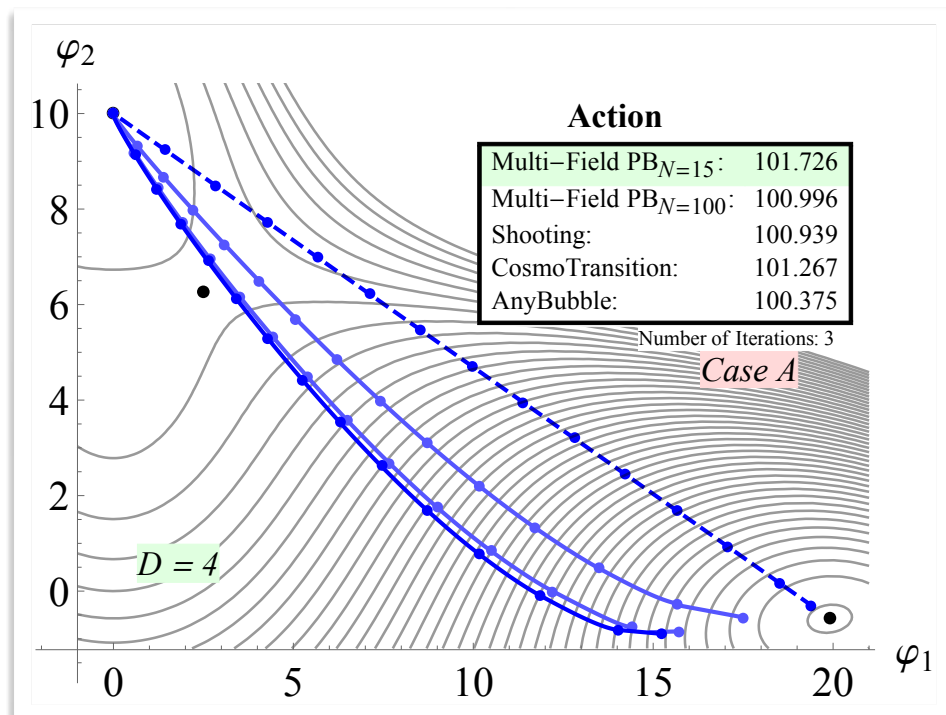


$$\delta S = 0 \rightarrow \bar{\varphi}(\rho)$$



Polygonal bounces

Guada, Maiezza, MN '18



FindBounce

Guada, MN, Pintar '20



# Bounce

Coleman '77

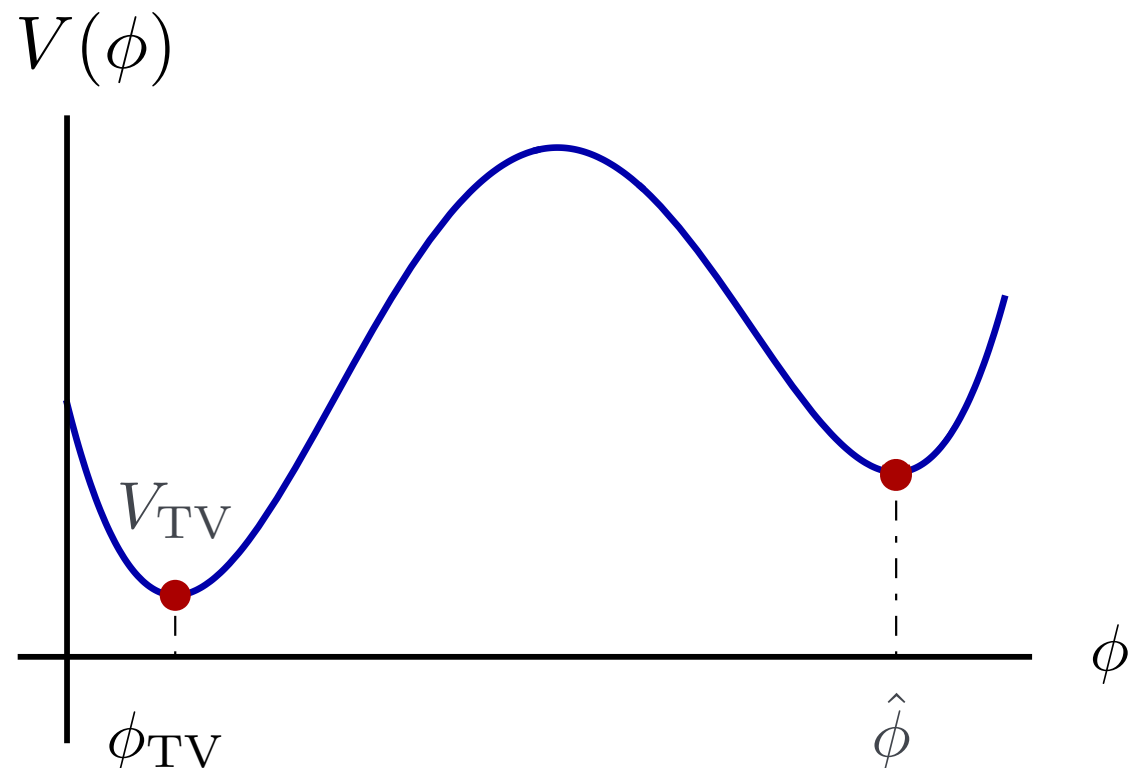
Action 
$$S = \Omega \int_0^\infty d\rho \rho^{D-1} \left( \frac{1}{2} \dot{\phi}^2 + V - \hat{V} \right),$$

$$\Omega = \frac{2\pi^{D/2}}{\Gamma(D/2)}$$

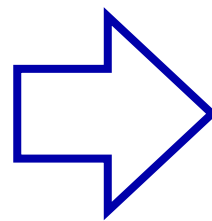
Extremize 
$$\ddot{\phi} + \frac{D-1}{\rho} \dot{\phi} = \frac{dV}{d\phi}$$

$$\phi(0) = \phi_{\text{in}}, \quad \phi(\infty) = \hat{\phi}$$

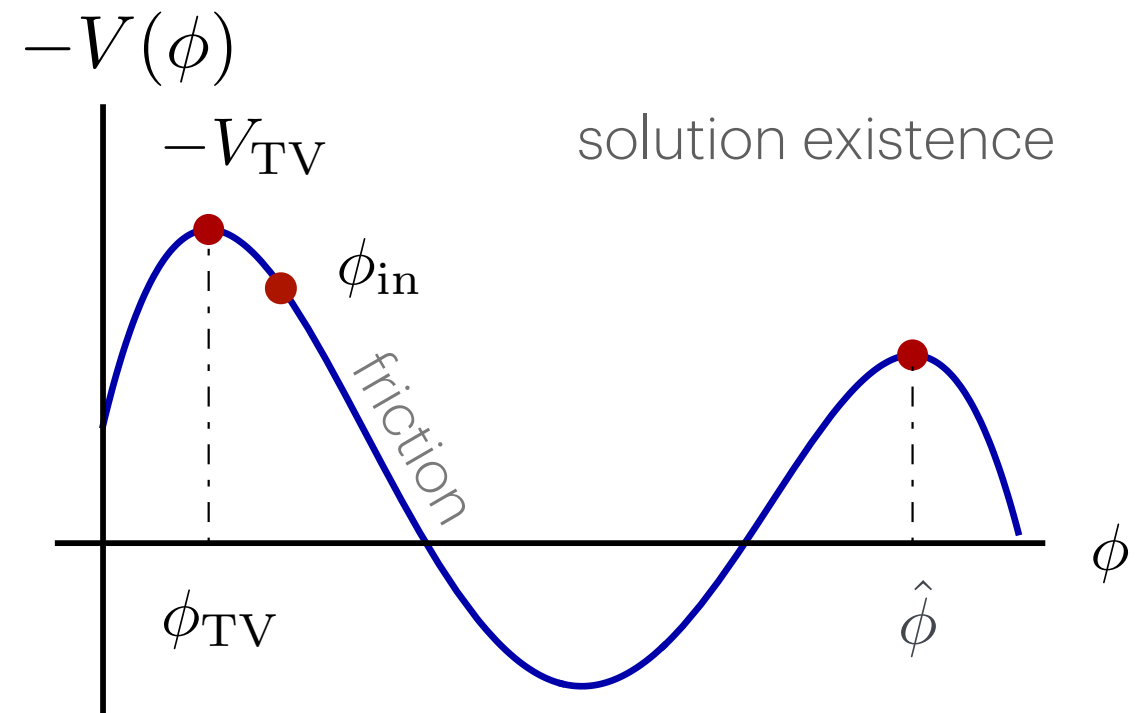
$$\dot{\phi}(0) = \dot{\phi}(\infty) = 0$$



particle  
analogy

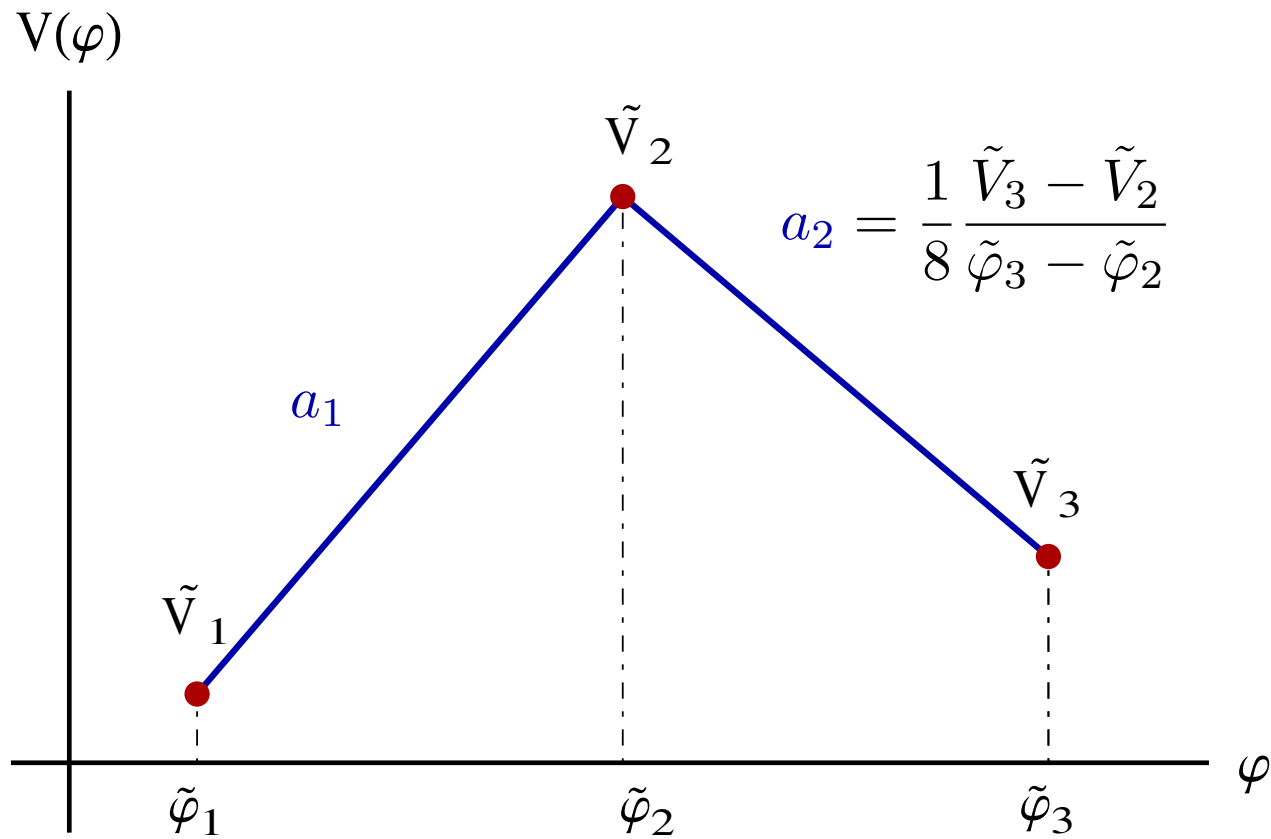


inverted  
potential



# Triangular

Duncan, Jensen '92



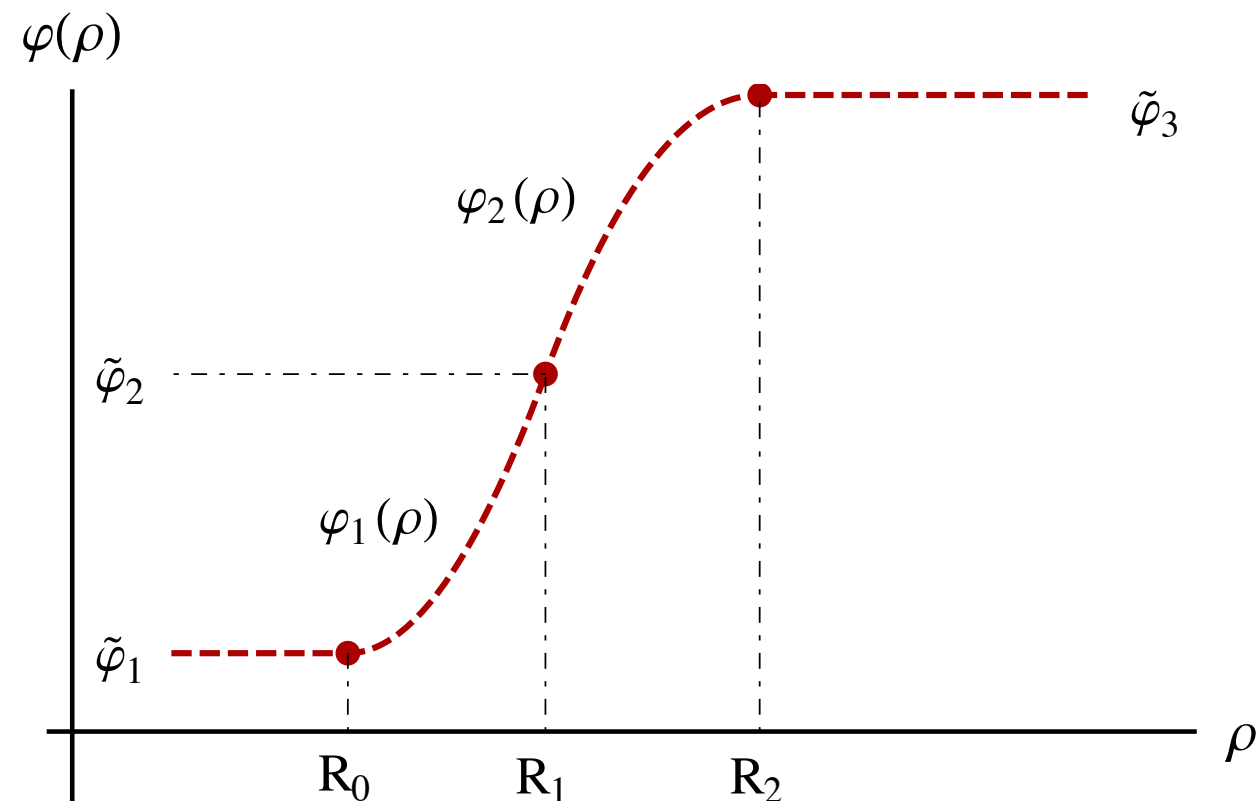
Linear potentials

● triangle and box

Exact solution

$$\ddot{\varphi} + \frac{3}{\rho} \dot{\varphi} = dV = 8a$$

$$\varphi = v + a\rho^2 + \frac{b}{\rho^2}$$



Initial conditions @  $R_0$

● a)  $\varphi_1(0) = \varphi_0, \quad \dot{\varphi}_1(0) = 0$

shoot in  $\varphi_0$

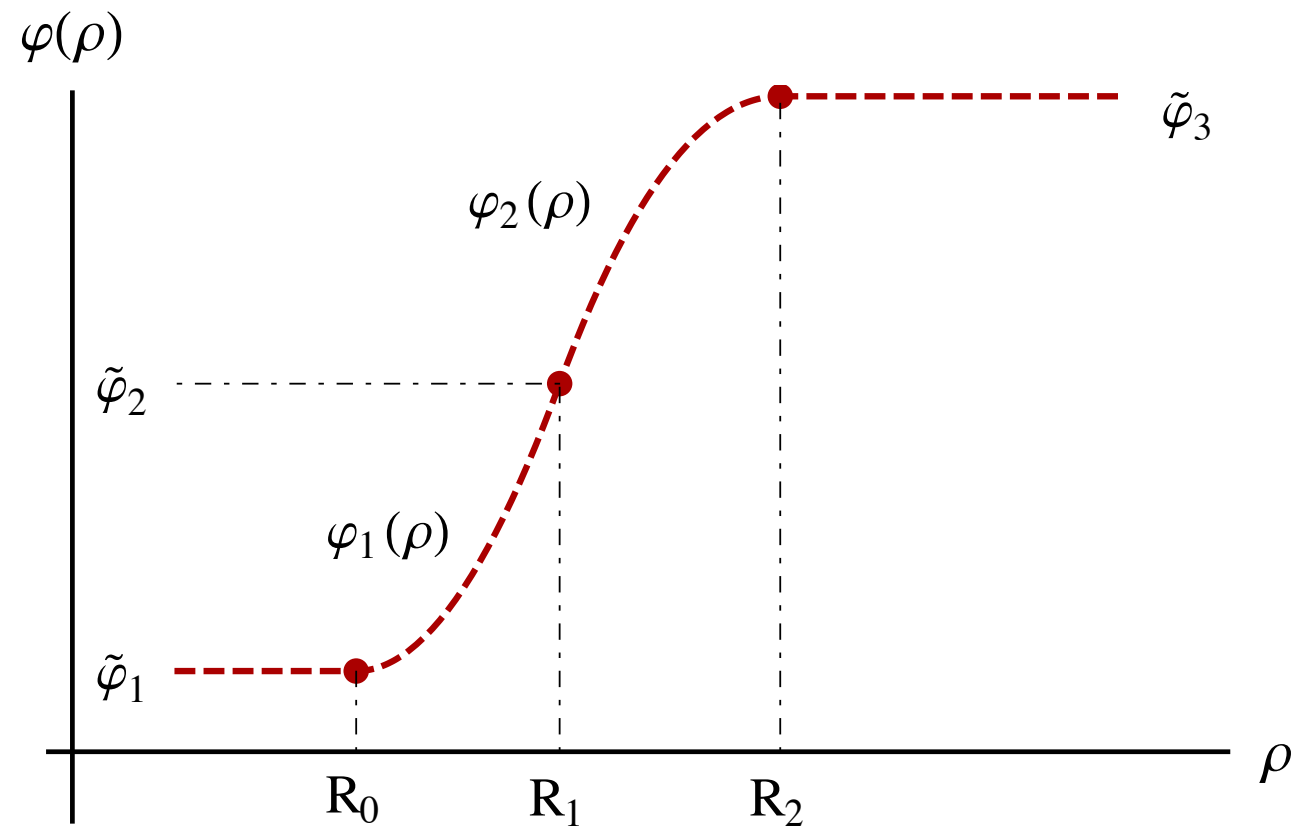
$$v_1 = \varphi_0, \quad b_1 = 0$$

● b)  $\varphi_1(R_0) = \tilde{\varphi}_1, \quad \dot{\varphi}_1(R_0) = 0$  or  $R_0$

$$v_1 = \tilde{\varphi}_1 - 2a_1 R_0^2, \quad b_1 = a_1 R_0^4$$



# Triangular



Matching conditions @  $R_1$

$$\varphi_1(R_1) = \varphi_2(R_1) = \tilde{\varphi}_2, \quad \dot{\varphi}_1(R_1) = \dot{\varphi}_2(R_1)$$

Final conditions @  $R_2$

$$\varphi_2(R_2) = \tilde{\varphi}_3, \quad \dot{\varphi}_2(R_2) = 0$$

$$v_2 = \tilde{\varphi}_3 - 2a_2 R_2^2, \quad b_2 = a_2 R_2^4$$

Complete solution - a) works in D-dimensions

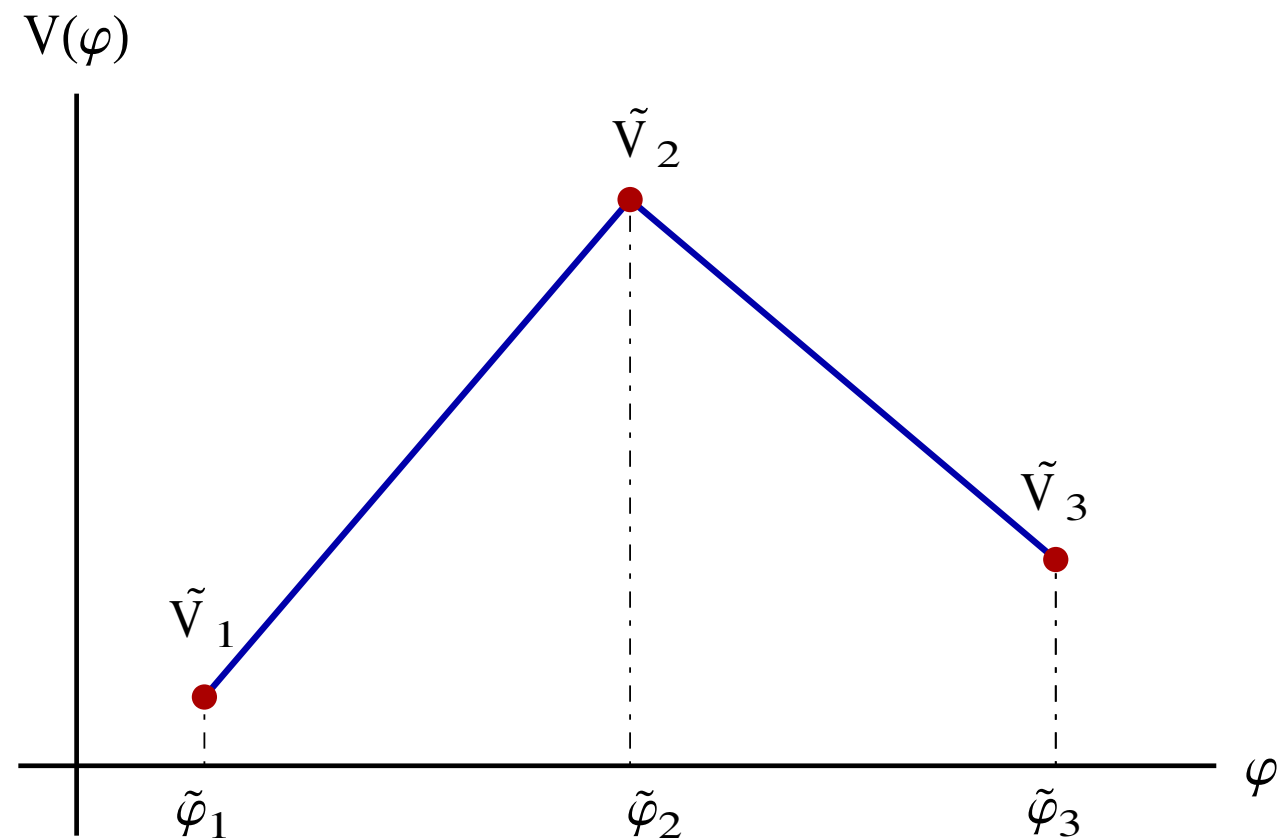
$$\bullet \text{ a) } \varphi_0 = \frac{\tilde{\varphi}_3 + c\tilde{\varphi}_2}{1+c}, \quad c = 2\frac{a_2 - a_1}{a_1} \left(1 - \sqrt{\frac{a_2}{a_2 - a_1}}\right) \quad R_1 = \sqrt{\frac{D}{4} \left(\frac{\tilde{\varphi}_2 - \varphi_0}{a_1}\right)}$$

---


$$\bullet \text{ b) } R_1 = \frac{1}{2} \frac{\tilde{\varphi}_3 - \tilde{\varphi}_1}{\sqrt{a_1(\tilde{\varphi}_2 - \tilde{\varphi}_1)} - \sqrt{-a_2(\tilde{\varphi}_3 - \tilde{\varphi}_2)}} \quad R_0^2 = R_1 \left( R_1 - \sqrt{\frac{\tilde{\varphi}_2 - \tilde{\varphi}_1}{a_1}} \right)$$

$$R_2^2 = R_1 \left( R_1 + \sqrt{\frac{\tilde{\varphi}_3 - \tilde{\varphi}_2}{-a_2}} \right)$$

# Triangular summary



Complete exact analytic solution

Solved in terms of Euclidean radius

Stable in thin wall, goes over to TWA  
with limited validity

Dutta, Hector, Konstandin,  
Vaudrevange, Westphal '12

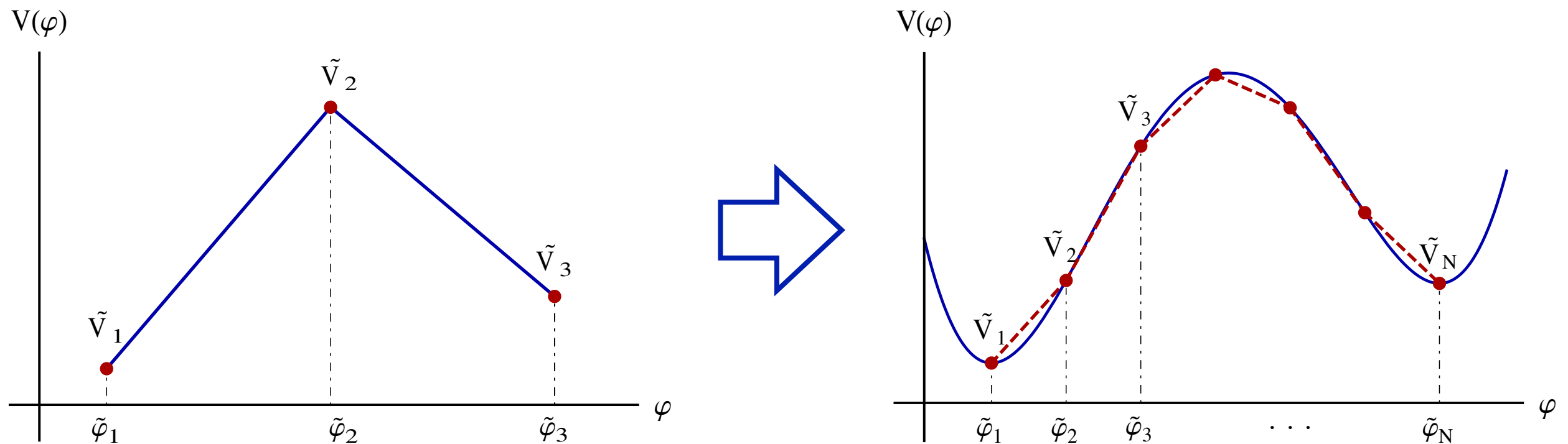
Analytic continuation in Minkowski space

describes the bubble evolution Pastras '11

Polygonal bounces

# Polygonal bounces

Extend to more segments and D dimensions

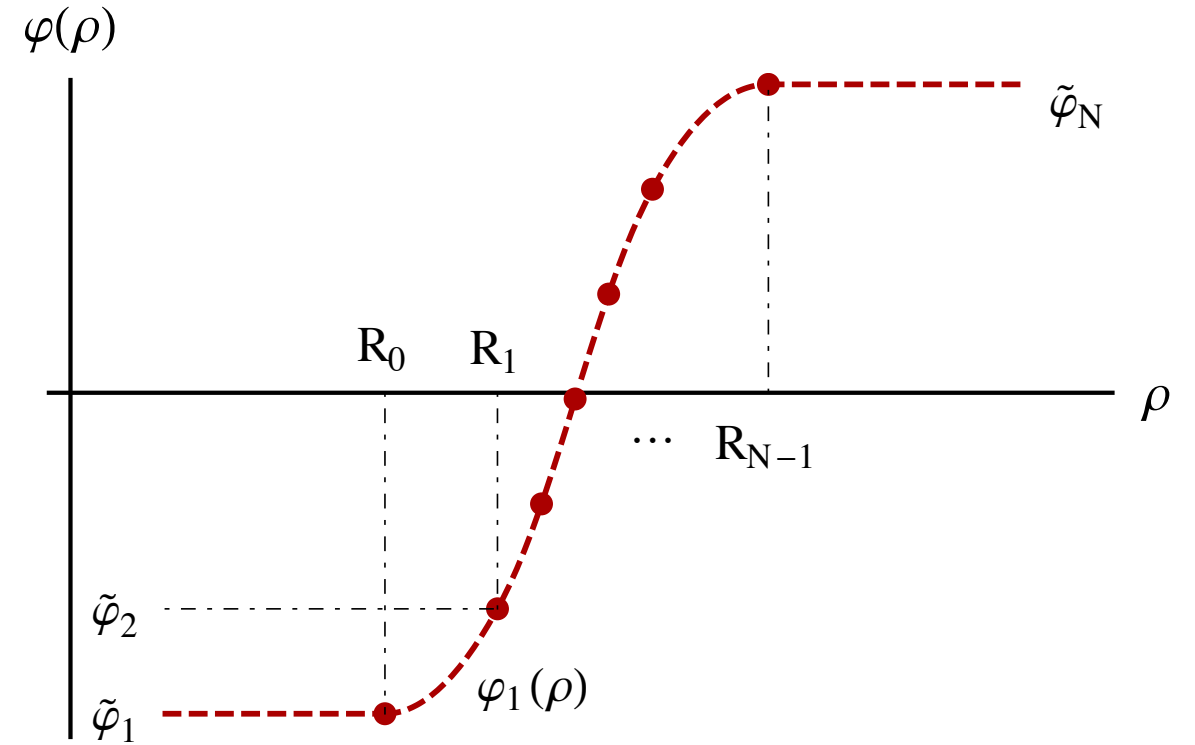
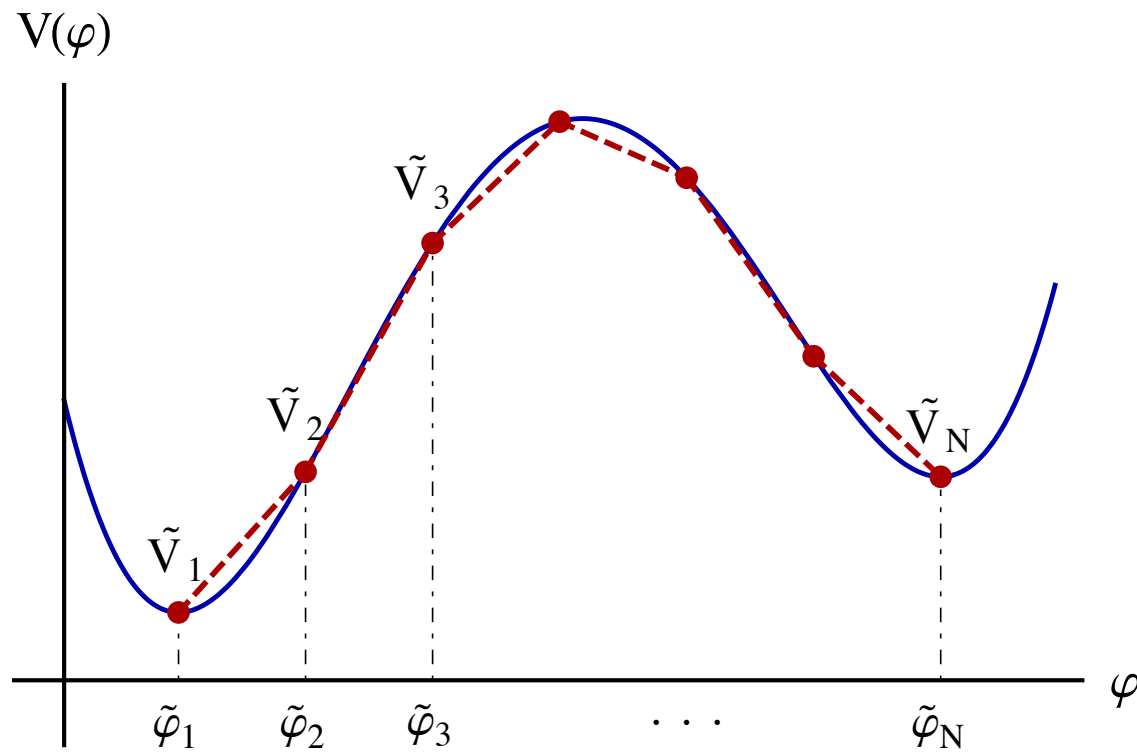


Approximates any  $V$  when  $N \rightarrow \infty$ , controlled precision

Geometric insight of segmentation, cover non-trivial features/unstable Vs

Semi-analytic solution for algebraic manipulation/deformation

# Polygonal bounces

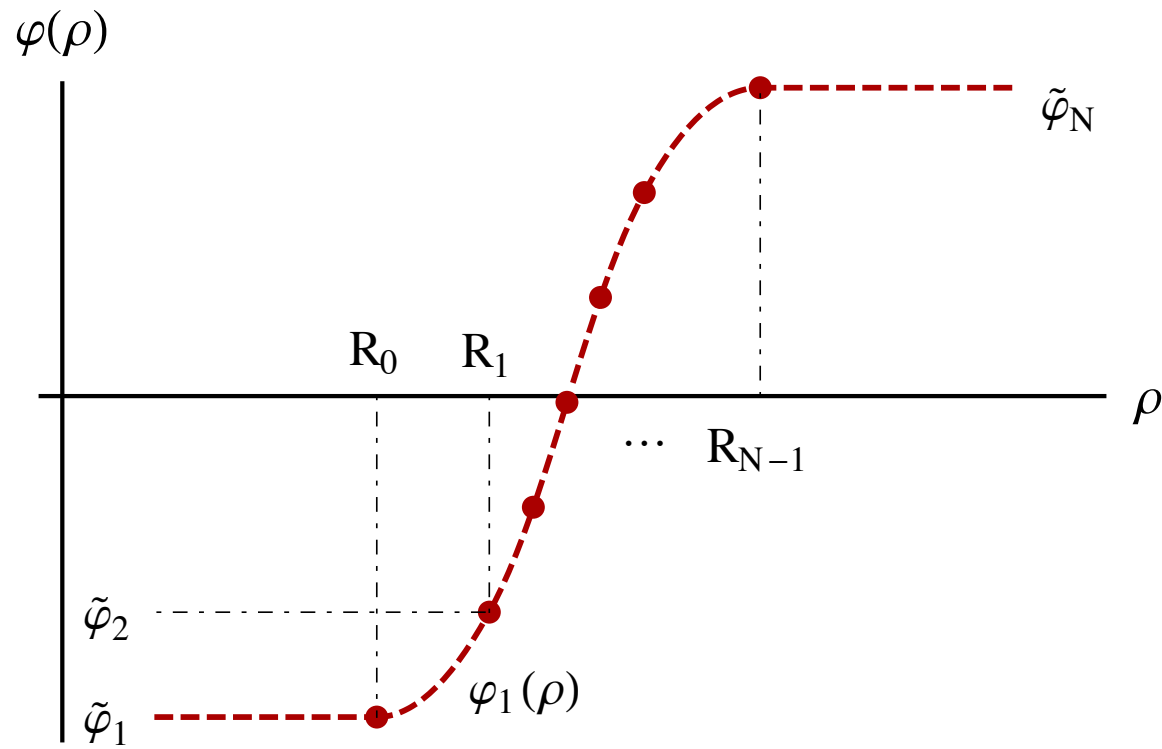


$$V_i(\varphi) = \underbrace{\left( \frac{\tilde{V}_{i+1} - \tilde{V}_i}{\tilde{\varphi}_{i+1} - \tilde{\varphi}_i} \right)}_{8a_i} (\varphi - \tilde{\varphi}_i) + \tilde{V}_i - \tilde{V}_N, \quad dV_i = 8a_i.$$

No free parameters, one segment three unknowns  $v_i, b_i, R_i$

Generalize case b), solve  $R_0$  or  $R_i$  a), retrieve  $\varphi_0$

# Polygonal construction



$$\ddot{\varphi}_i + \frac{D-1}{\rho} \dot{\varphi}_i = dV_i = 8a_i$$

$$\varphi_i = v_i + \frac{4}{D} a_i \rho^2 + \frac{2}{D-2} \frac{b_i}{\rho^{D-2}}$$

Initial/final conditions remain the same

Matching conditions @  $R_i$

3 parameters and 3 unknowns/segment

$$\varphi_i(R_1) = \varphi_{i+1}(R_i) = \tilde{\varphi}_{i+1}, \quad \dot{\varphi}_i(R_i) = \dot{\varphi}_{i+1}(R_i)$$

The bounce defined recursively

• a)  $R_0 = 0$

• b)  $\varphi_0 = \tilde{\varphi}_1$

$$v_n = \varphi_0 - \frac{4}{D-2} \left( a_1 R_0^2 + \sum_{i=1}^{n-1} (a_{i+1} - a_i) R_i^2 \right)$$

$$b_n = \frac{4}{D} \left( a_1 R_0^D + \sum_{i=1}^{n-1} (a_{i+1} - a_i) R_i^D \right)$$

Radii computed at each segment from matching the fields

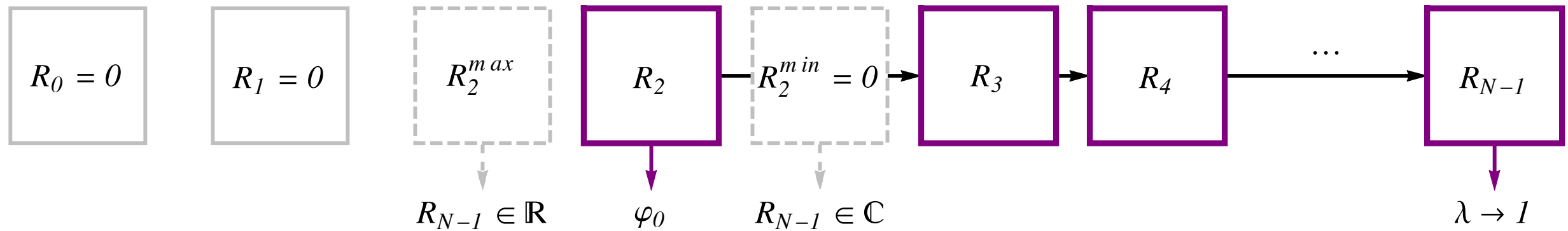
$$\varphi_n(R_n) = \tilde{\varphi}_{n+1}$$

Fewnomials

$$R_n^D - \frac{D}{4} \frac{\delta_n}{a_n} R_n^{D-2} + \frac{D}{2(D-2)} \frac{b_n}{a_n} = 0$$

$$\delta_n = \tilde{\varphi}_{n+1} - v_n$$

require real positive roots





Radii computed at each segment from matching the fields

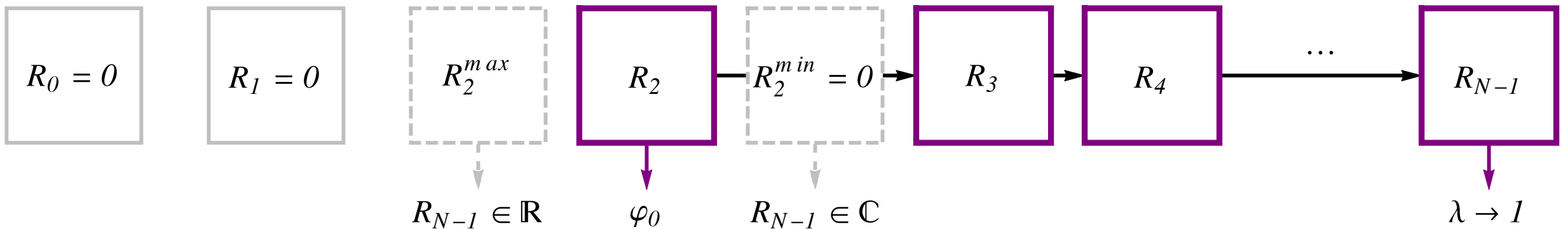
$$\varphi_n(R_n) = \tilde{\varphi}_{n+1}$$

Fewnomials

$$R_n^D - \frac{D}{4} \frac{\delta_n}{a_n} R_n^{D-2} + \frac{D}{2(D-2)} \frac{b_n}{a_n} = 0$$

$$\delta_n = \tilde{\varphi}_{n+1} - v_n$$

require real positive roots



radii solutions

$$D = 3 : \quad 2R_n = \frac{1}{\sqrt{a_n}} \left( \frac{\delta_n}{\xi} + \xi \right), \quad \xi^3 = \sqrt{36a_n b_n^2 - \delta_n^3} - 6\sqrt{a_n b_n},$$

simple cubic

$$D = 4 : \quad 2R_n^2 = \frac{1}{a_n} \left( \delta_n + \sqrt{\delta_n^2 - 4a_n b_n} \right) \quad \text{quadratic}$$

$D = 2, 6, 8$  in the paper, other  $D$ s possible numerically Amariti '20

# Bounce action

Euclidean action

$$S_D = \frac{2\pi^{\frac{D}{2}}}{\Gamma\left(\frac{D}{2}\right)} \int_0^\infty \rho^{D-1} d\rho \left( \frac{1}{2} \dot{\varphi}^2 + V(\varphi) \right)$$

PB action

$$S_{>2} = \frac{2\pi^{\frac{D}{2}}}{\Gamma\left(\frac{D}{2}\right)} \left\{ \frac{R_0^D}{D} (\tilde{V}_1 - \tilde{V}_N) + \sum_{i=1}^{N-1} \left[ \rho^2 \left( \frac{32a_i^2(D+1)\rho^D}{D^2(D+2)} + \frac{16a_i b_i}{D(D-2)} - \frac{2b_i^2}{\rho^D(D-2)} \right) + \frac{\rho^D}{D} \left( 8a_i(v_i - \tilde{\varphi}_i) + \tilde{V}_i - \tilde{V}_N \right) \right]_{R_{i-1}}^{R_i} \right\}$$

Total

$$S = \mathcal{T} + \mathcal{V}$$

$$\mathcal{T} \propto \int_0^\infty \rho^{D-1} d\rho \dot{\varphi}^2,$$

kinetic

$$\mathcal{V} \propto \int_0^\infty \rho^{D-1} d\rho V(\varphi)$$

potential

# Derrick's theorem

Non-existence of non-trivial static solutions of  
KG equation, no solitonic scalar 'particles'

Derrick '64

Unstable under re-scaling

$$\varphi(\rho) \rightarrow \varphi(\rho/\lambda)$$

$$\begin{aligned}\lambda \times 0 &= 0, \\ \lambda \times \infty &= \infty\end{aligned}$$

change of variables,  
int. limits remain the same

$$S_D^{(\lambda)} = \lambda^{D-2}\mathcal{T} + \lambda^D\mathcal{V}$$

action is extremized  
at non-scaled values  
for true solutions

$$\left. \frac{dS_D^{(\lambda)}}{d\lambda} \right|_{\lambda=1} = 0$$

$$(D-2)\mathcal{T} + D\mathcal{V} = 0$$

relation between kinetic and potential

$$\left. \frac{d^2 S_D^{(\lambda)}}{d\lambda^2} \right|_{\lambda=1} < 0$$

Caveat for PB

$$R \rightarrow \lambda R$$

Works for  $N \gg 1$

# Benchmarks

Linearly off-set quartic potential

Coleman '77

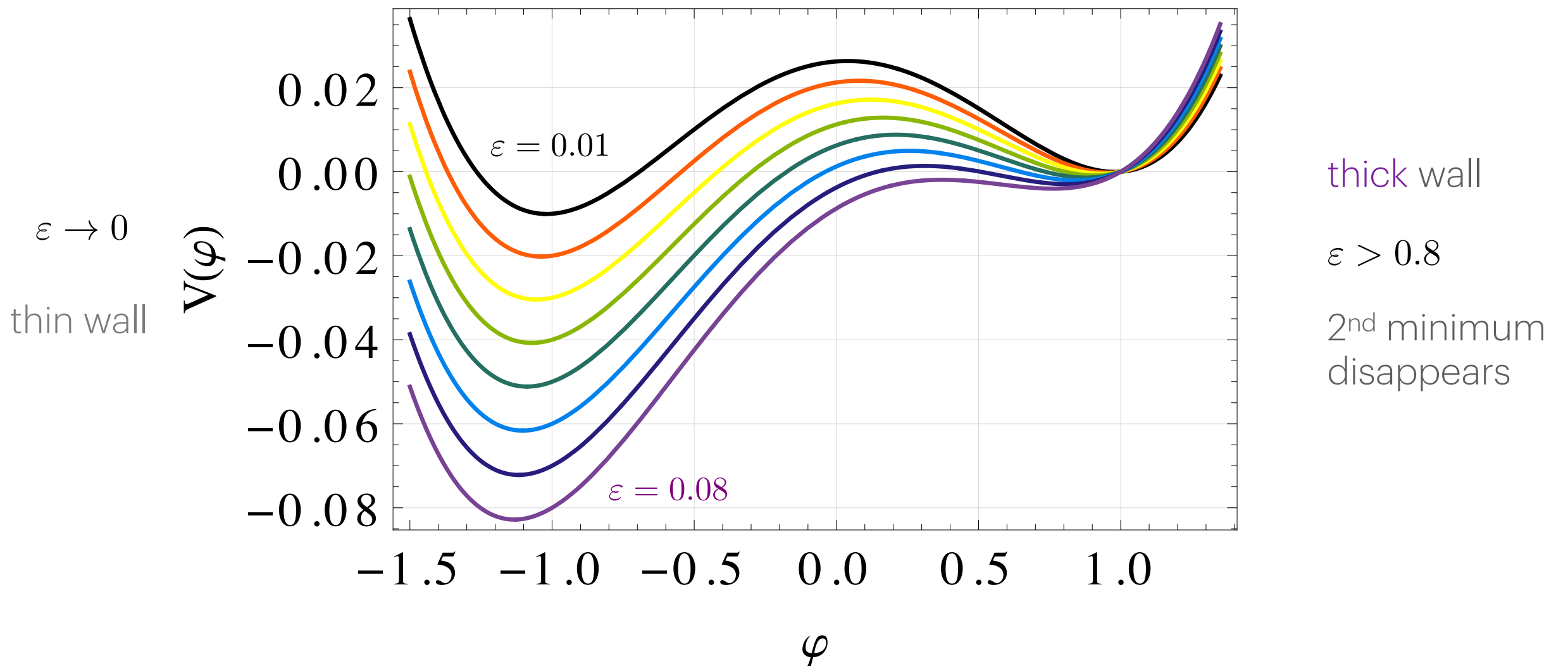
$$V(\varphi) = \frac{\lambda}{8} (\varphi^2 - v^2)^2 + \varepsilon \left( \frac{\varphi - v}{2v} \right)$$

Benchmark for testing

$\lambda = 0.25, \quad v = 1$

rescaling

Sarid '98



# Euclidean action, comparisons

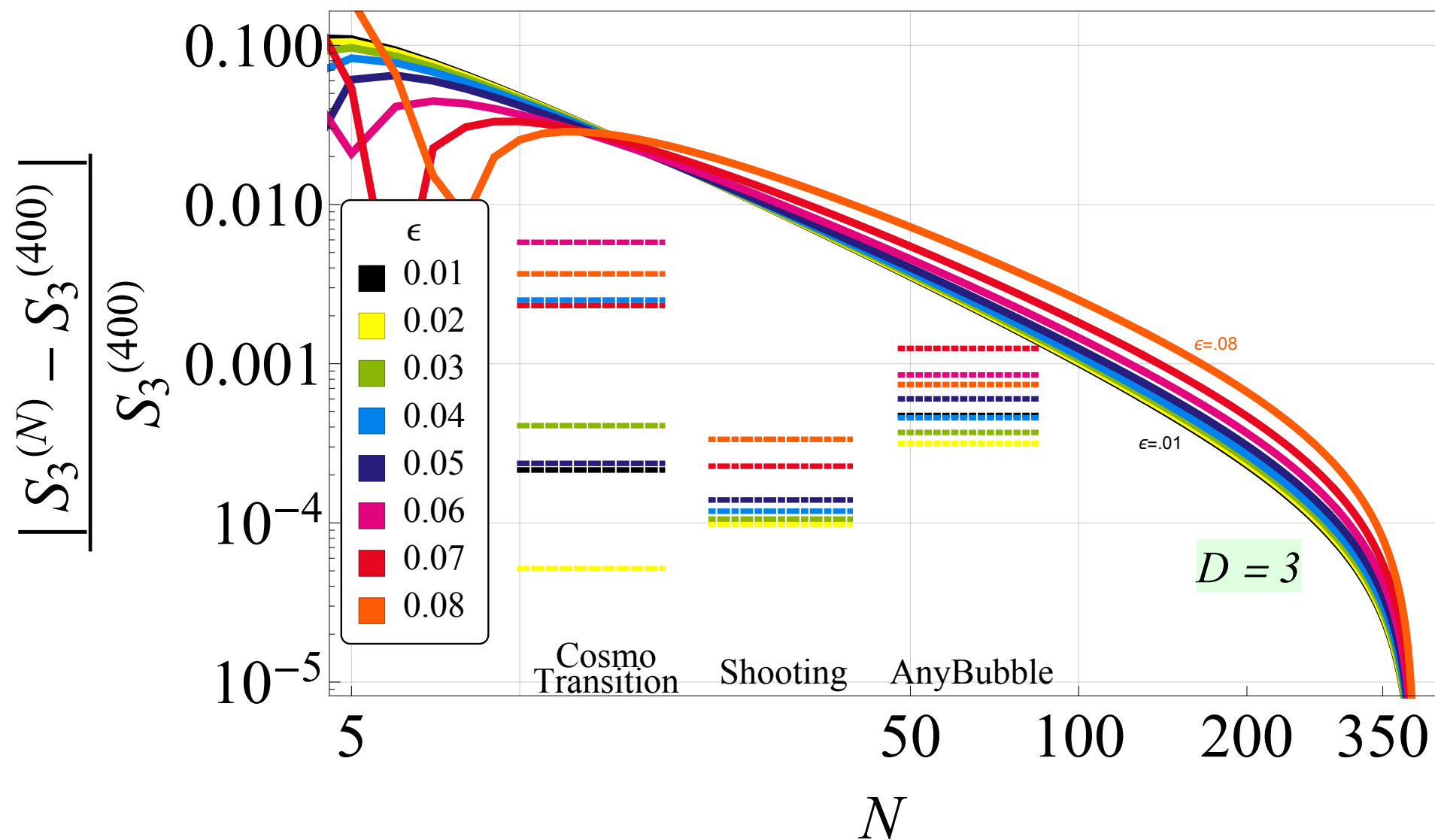
● CosmoTransitions Runge-Kutta PDE solver, initial value approximations

Wainwright '11

● AnyBubble multiple shooting, damping approximations

Masoumi, Olum, Shlaer '16

● Shooting Mathematica, precise setting of initial values, issues with 0, infinity



PB within permille after 100 iterations

stable for thin/thick

faster convergence for thin wall

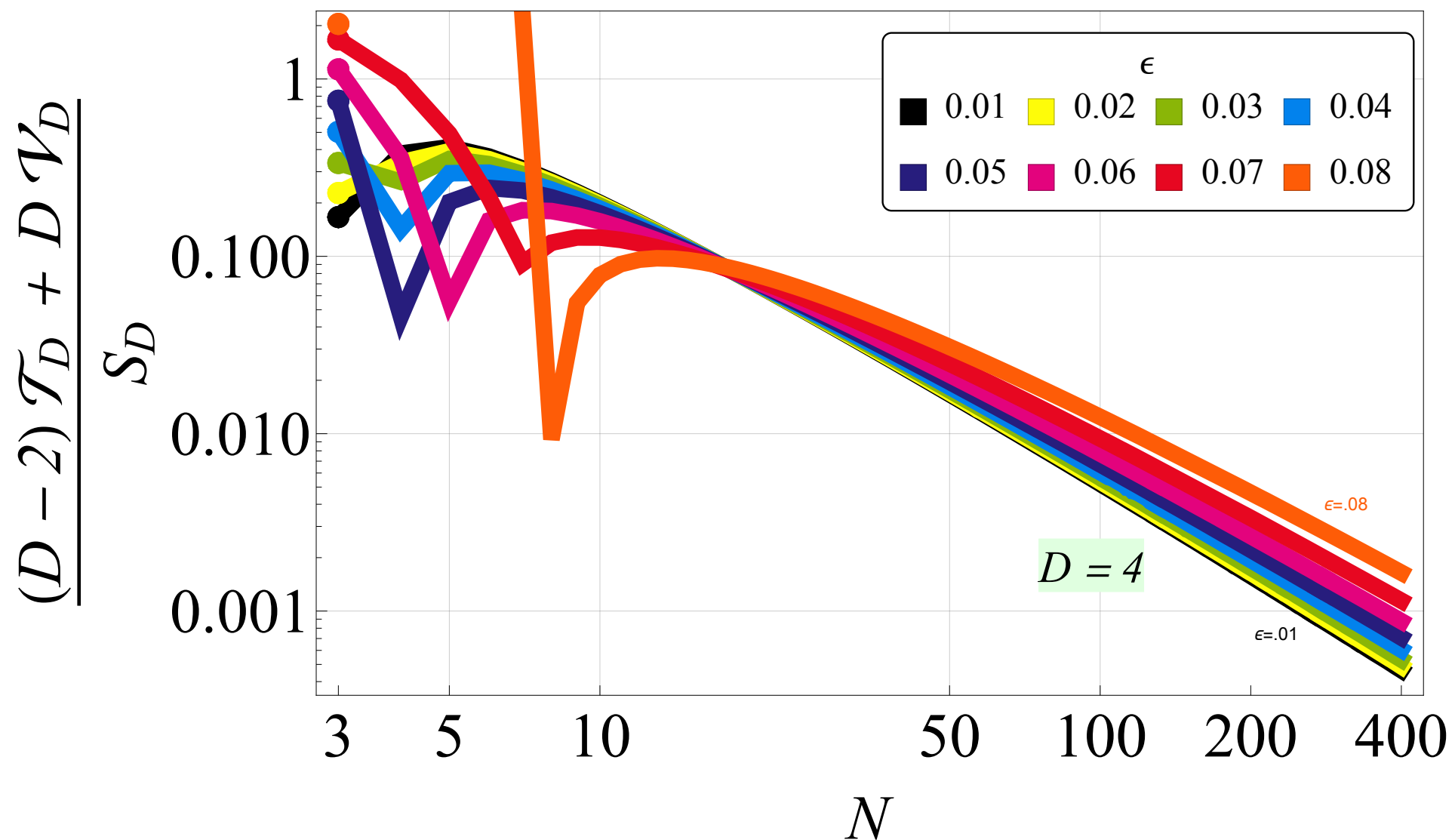
Derrick's theorem

$$(D - 2)\mathcal{T} + D\mathcal{V} \rightarrow 0$$

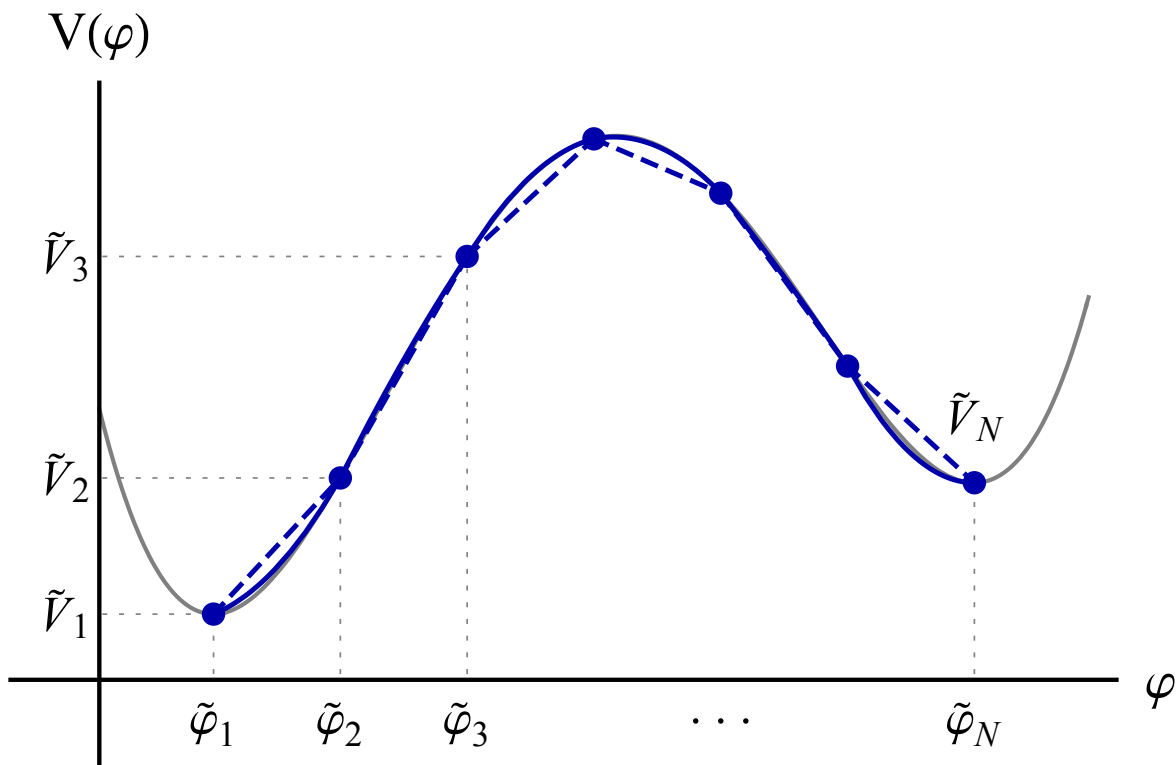
finite part corrections up to  $N \simeq 10$

independent measure of goodness of approximation

above relation 'exact' for the PB potential



# Higher orders



Expand to higher orders

- improves convergence
- important @ extrema

$$\begin{aligned}
 \text{---} & V_i \simeq \tilde{V}_i - \tilde{V}_N + \partial \tilde{V}_i (\varphi_i - \tilde{\varphi}_i) \\
 \text{---} & + \frac{\partial^2 \tilde{V}_i}{2} (\varphi_i - \tilde{\varphi}_i)^2
 \end{aligned}$$

Perturbative expansion  $\varphi = \varphi_{PB} + \xi$

$$\ddot{\varphi} + \frac{D-1}{\rho} \dot{\varphi} = 8(a + \alpha) + \delta dV(\varphi_{PB}(\rho))$$

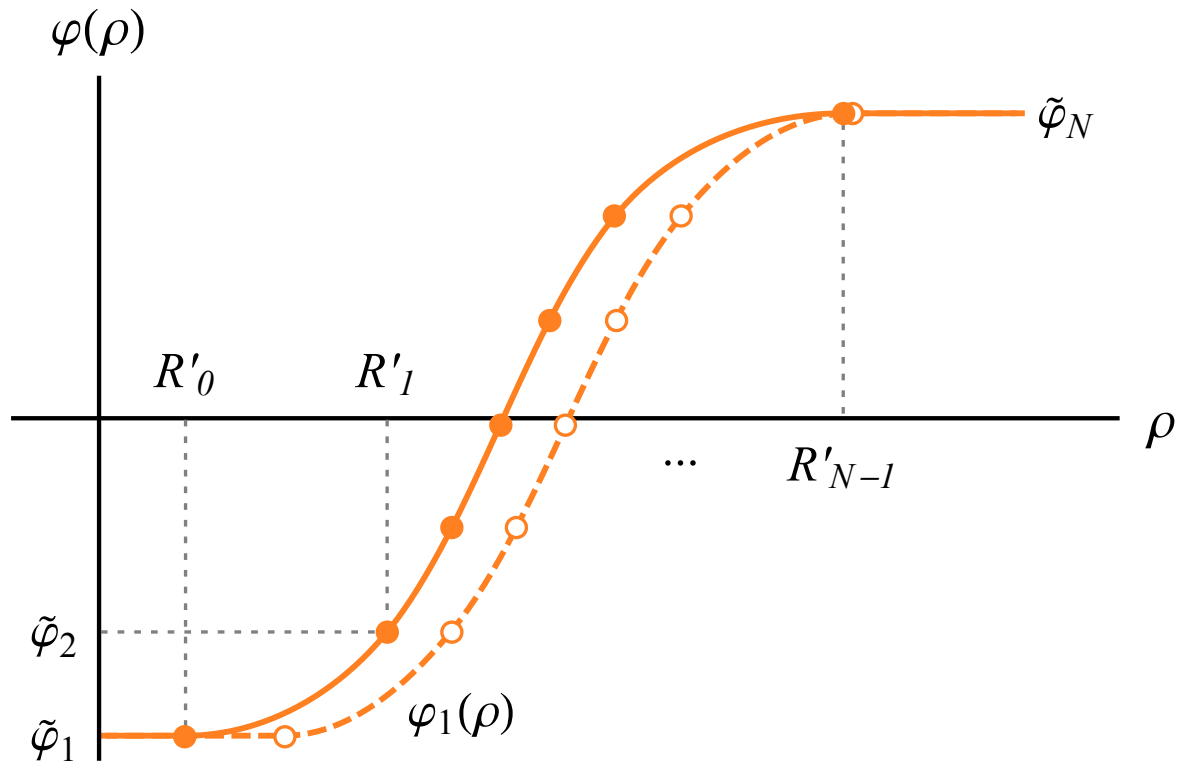
$$\ddot{\xi} + \frac{D-1}{\rho} \dot{\xi} = 8\alpha + \delta dV(\rho)$$

$$\xi = \nu + \frac{2}{D-2} \frac{\beta}{\rho^{D-2}} + \frac{4}{D} \alpha \rho^2 + \mathcal{I}(\rho)$$

$$\mathcal{I}_s^{D=4} = \partial^2 \tilde{V}_s \left( \frac{v_s - \tilde{\varphi}_s}{8} \rho^2 + \frac{b_s}{2} \ln \rho + \frac{a_s}{24} \rho^4 \right)$$



# Higher orders



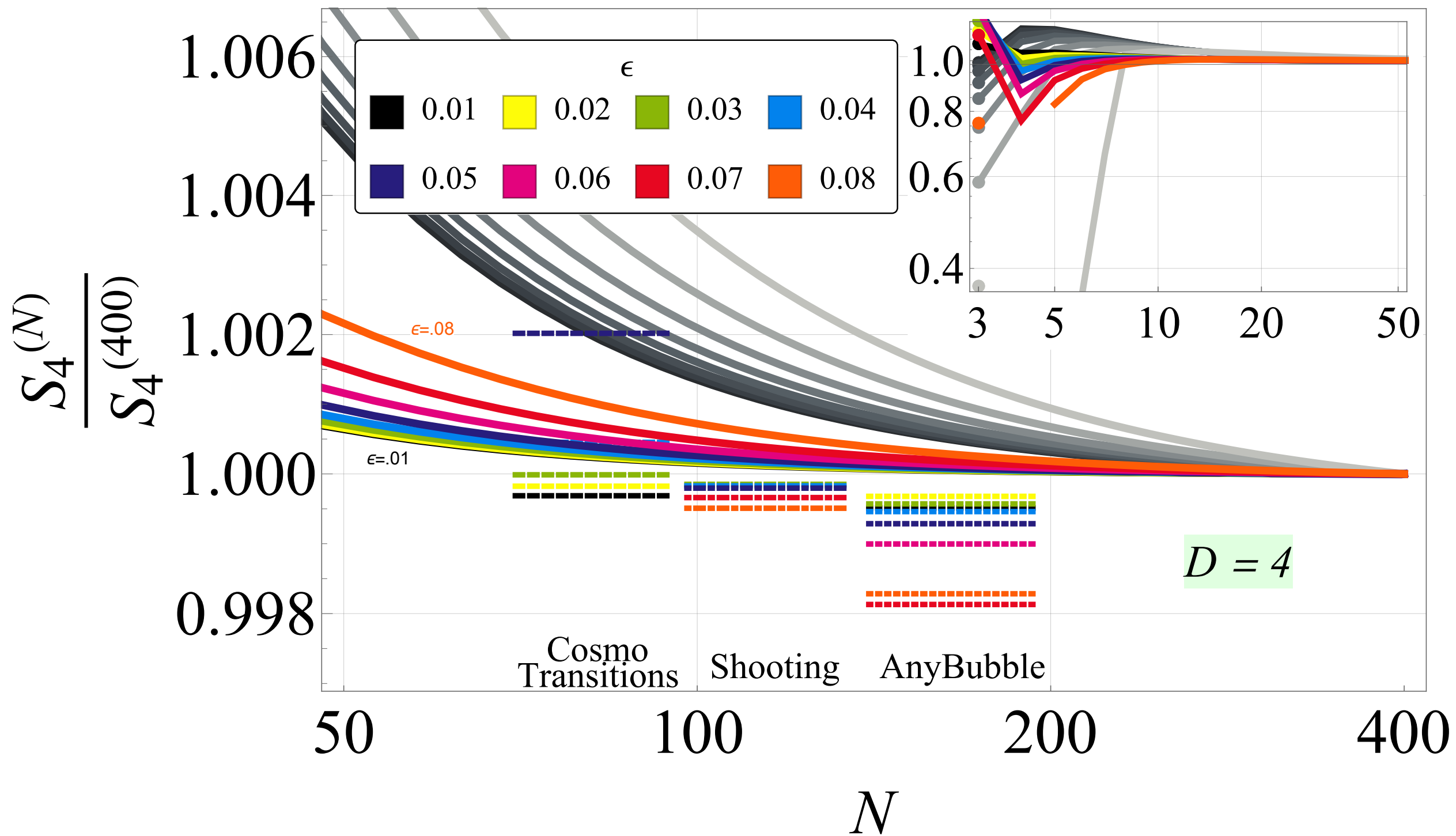
Match at perturbed radii

$$R_s \rightarrow R_s (1 + r_s), \quad r_s \ll 1$$

Rederive the matching conditions

A single linear equation = very fast

$$r_s = \frac{\beta_s + \frac{D-2}{2} (\nu_s + \mathcal{I}_s + \frac{4}{D} \alpha_s R_s^2) R_s^{D-2}}{(D-2) (b_s - \frac{4}{D} a_s R_s^D)}$$



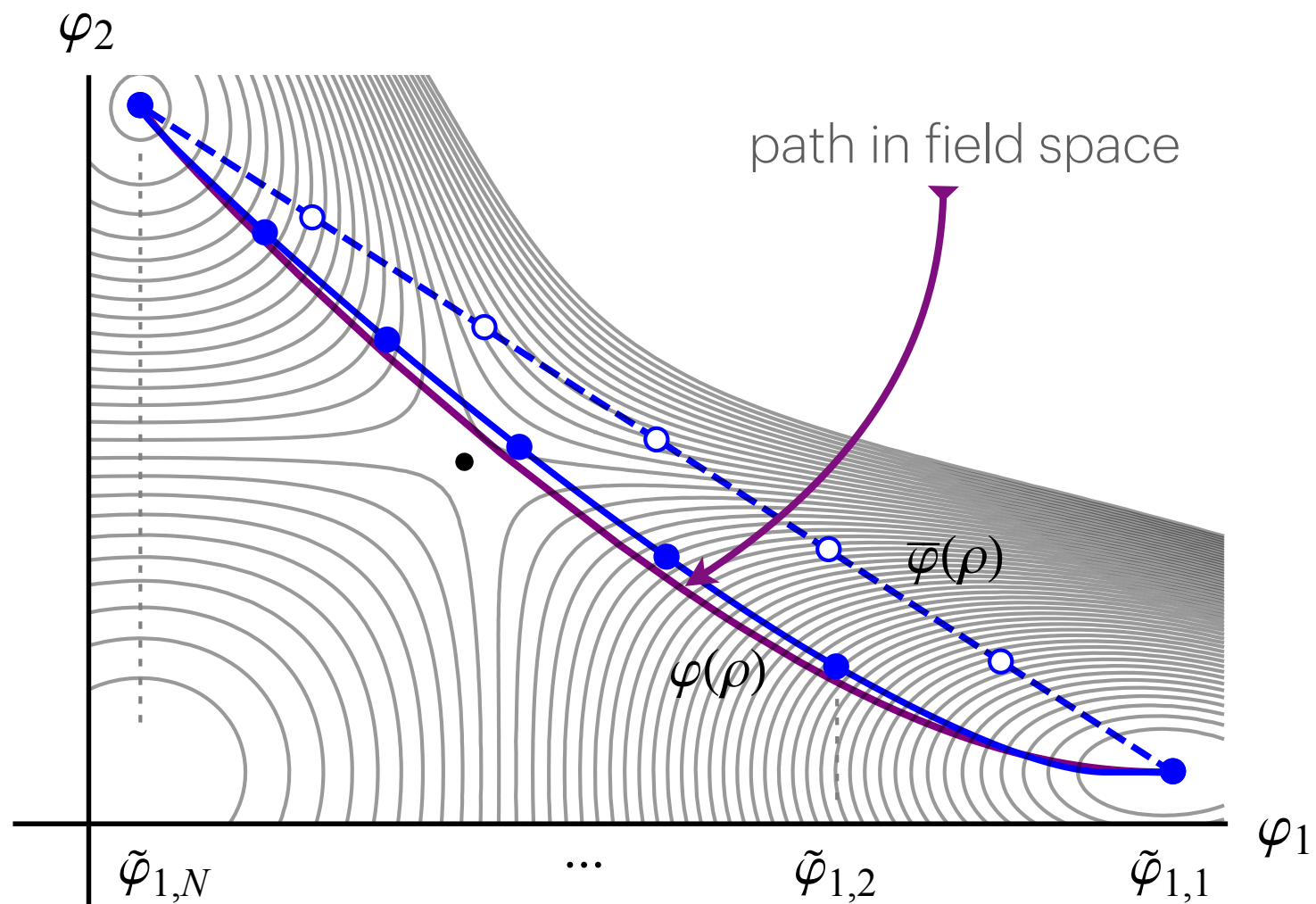
# Multi-fields

$$\ddot{\varphi}_i + \frac{D-1}{\rho} \dot{\varphi}_i = \frac{dV}{d\varphi_i}$$

$$\varphi_i(0) = \varphi_{0i}$$

Shooting method impractical

- highly non-linear
- multi-dimensional field space



# Multi-fields

$$\ddot{\varphi}_i + \frac{D-1}{\rho} \dot{\varphi}_i = \frac{dV}{d\varphi_i}$$

$$\varphi_i(0) = \varphi_{0i}$$

- CosmoTransitions Wainwright '11

bounce and path deformation separate, oscillations, Runge-Kutta PDE solver

- AnyBubbleMasoumi, Olum, Shlaer '16

multiple shooting, damping approximations

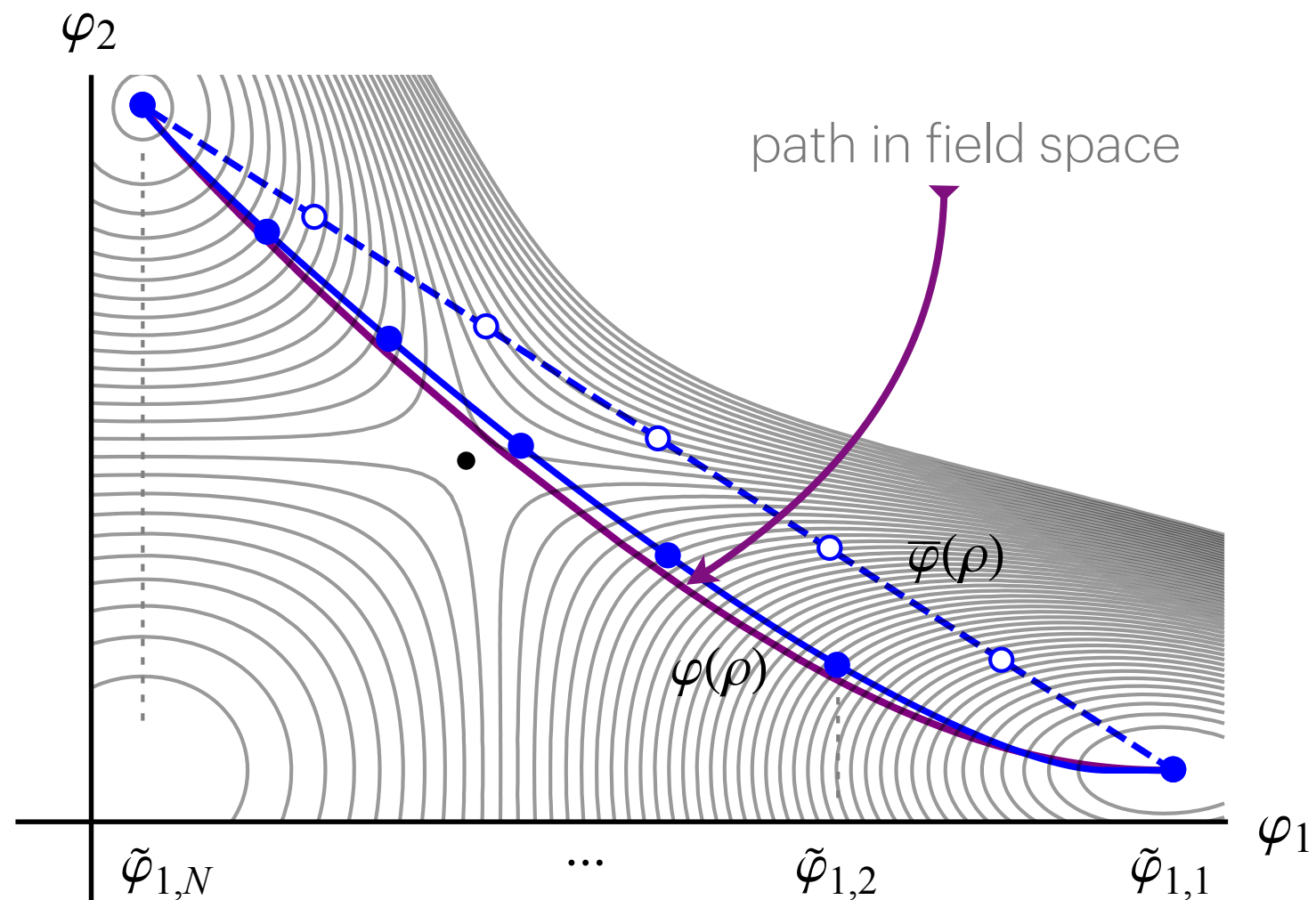
- Other approaches

tunnelling potential

Espinosa, Konstandin '18

machine learning

Piscopo, Spannowsky, Waite '19

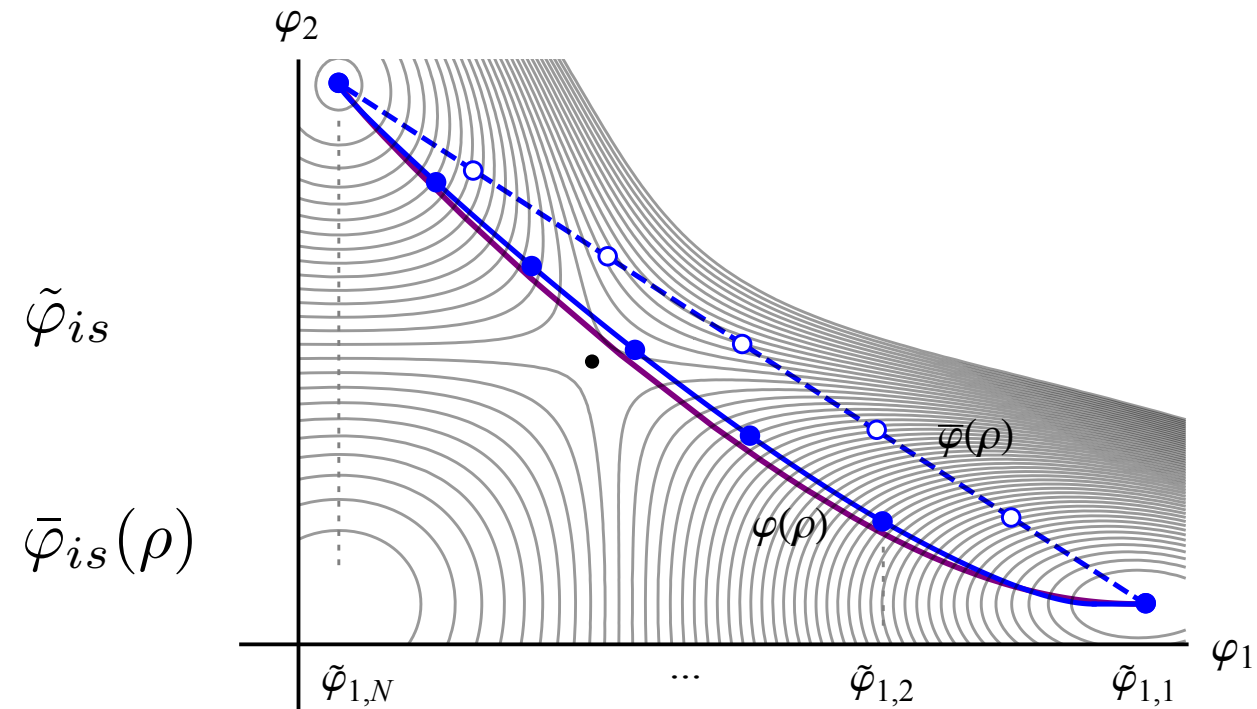


gradient flow

Sato '19

# Polygonal approach with many fields

- Initial ansatz      straight line, via saddle, custom segmentation
- Initial solution    longitudinal single field PB



## Crucial idea #1

- perturbation up to linear term in \$V\$, keeps the PB

$$\underbrace{\ddot{\tilde{\varphi}}_{is} + \frac{D-1}{\rho} \dot{\tilde{\varphi}}_{is}}_{8\bar{a}_{is}} + \underbrace{\ddot{\zeta}_{is} + \frac{D-1}{\rho} \dot{\zeta}_{is}}_{8a_{is}} = \frac{dV}{d\varphi_i} (\bar{\varphi} + \zeta)$$

$$\zeta_{is} = v_{is} + \frac{2}{D-2} \frac{b_{is}}{\rho^{D-2}} + \frac{4}{D} a_{is} \rho^2$$

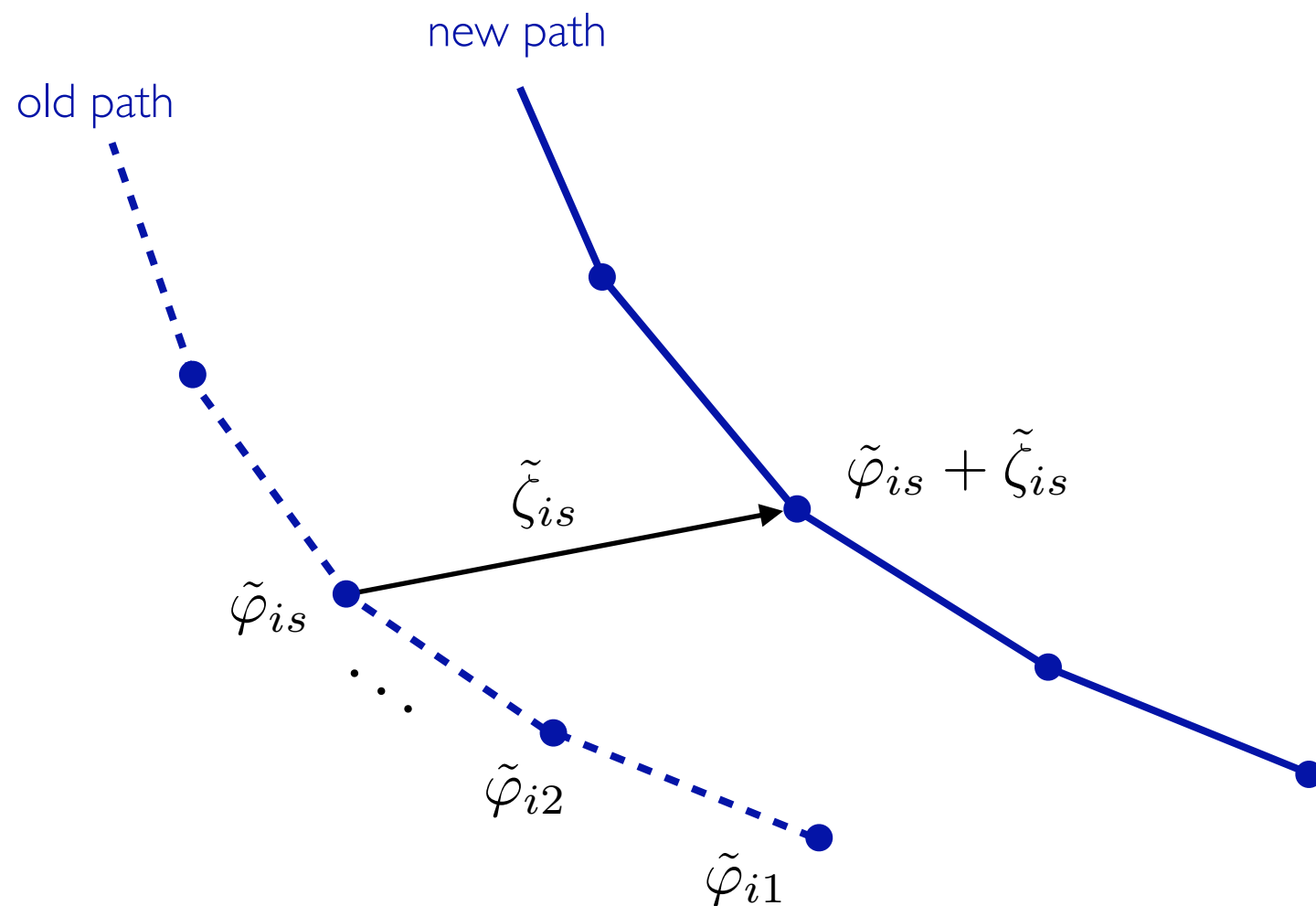
$$\underbrace{\ddot{\varphi}_{is} + \frac{D-1}{\rho} \dot{\varphi}_{is}}_{8\bar{a}_{is}} + \underbrace{\ddot{\zeta}_{is} + \frac{D-1}{\rho} \dot{\zeta}_{is}}_{8a_{is}} = \frac{dV}{d\varphi_i} (\bar{\varphi} + \zeta)$$

Crucial idea #2

$$8a_{is} \simeq \frac{dV}{d\varphi_i} (\tilde{\varphi}_{is} + \tilde{\zeta}_{is}) - 8\bar{a}_{is}$$

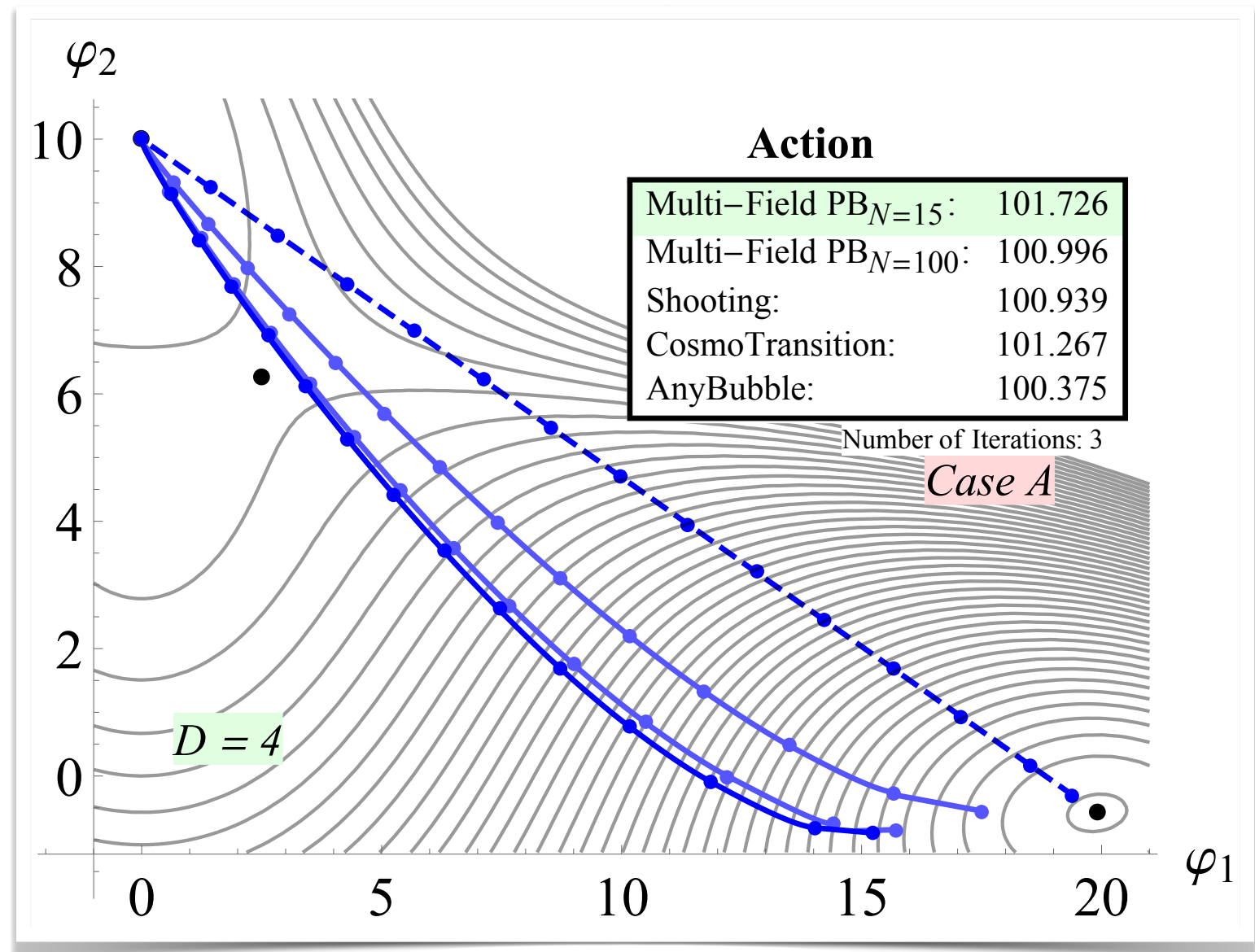
$$\frac{dV}{d\varphi_i} \simeq \frac{1}{2} \left( d_i \tilde{V}_s + d_i \tilde{V}_{s+1} + d_{ij}^2 \tilde{V}_s \tilde{\zeta}_{js} + d_{ij}^2 \tilde{V}_{s+1} \tilde{\zeta}_{js+1} \right)$$

- simultaneous solution for the bounce and path deformation
- linear system for  $r_{i0}$  (as in the single field expansion) and  $\tilde{\zeta}_{is}$
- iterate until  $\tilde{\zeta}_{is} < \varepsilon_{\Delta\varphi}$



$$V(\varphi_i) = \sum_{i=1}^2 (-\mu_i^2 \varphi_i^2 + \lambda_i^2 \varphi_i^4) + \lambda_{12} \varphi_1^2 \varphi_2^2 + \tilde{\mu}^3 \varphi_2$$

- no oscillations
- converges in a few iterations
- works for thin wall
- works for  $D=3$  and 4
- tested for up to 20 fields



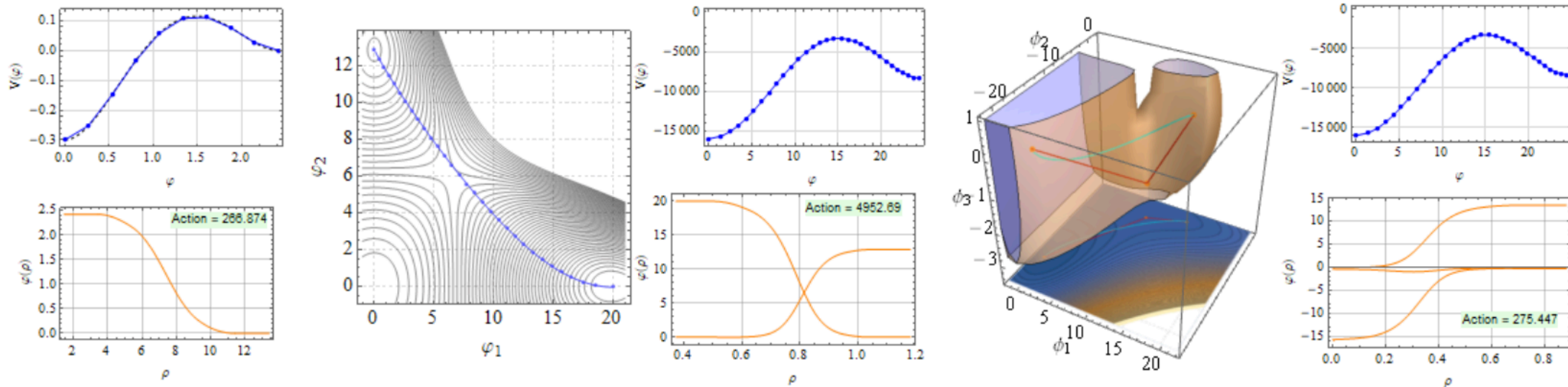


FindBounce

# FindBounce <https://github.com/vguada/FindBounce/releases>

*FindBounce* is a [Mathematica](#) package that computes the bounce configuration needed to compute the false vacuum decay rate with multiple scalar fields.

We kindly ask the users of the package to cite the two papers that describe the working of the *FindBounce* package: the paper with the original proposal by [Guada, Maiezza and Nemevšek \(2019\)](#) and the software release manual by [Guada, Nemevšek and Pintar \(2020\)](#).



## Installation

To use the *FindBounce* package you need Mathematica version 10.0 or later. The package is released in the `.paclet` file format that contains the code, documentation and other necessary resources. Download the latest `.paclet` file from the repository ["releases"](#) page to your computer and install it by evaluating the following command in the Mathematica:

```
(* Path to .paclet file downloaded from repository "releases" page. *)
PacletInstall["full/path/to/FindBounce-X.Y.Z.paclet"]
```

Load the package as usual

```
In[1]:= Needs["FindBounce`"]
```

Define a metastable potential

```
In[2]:= V[x_] := 0.5 x^2 + 0.5 x^3 + 0.12 x^4;
```

```
In[3]:= extrema = x/.Sort@Solve[D[V[x],x]==0];
```

Compute the bounce - obtain bf = the bounce function

```
In[4]:= bf = FindBounce[V[x],x,{extrema[[1]],extrema[[3]]}]
```

```
Out[4]= BounceFunction[  Action: 73500.  
Dimension: 4 ]
```

```
In[5]:= bf["Action"]
```

```
Out[5]= 73496.
```

```
In[6]:= bf["Dimension"]
```

Retrieve the  
bounce properties

```
Out[6]= 4
```

Run on single points

```
FindBounce[{{x1,V1},{x2,V2},...}]
```

And multifiends

```
FindBounce[V[x,y,...],{x,y,...},{m1,m2}]
```

## Custom options control the input

`"Dimension"`

sets the Euclidean spacetime dimension, 3 or 4

`"FieldPoints"`

number of field points defines the segmentation

`"Gradient"`

one can pre-calculate the gradient, or make it numerical

`"Hessian"`

similar to the gradient, needed for multi-fields

`"MaxPath"`

limits the number of path iterations, typically small

`"MidFieldPoint"`

one can define a starting fixed point (e.g. the saddle)

`"PathTolerance"` &  
`"ActionTolerance"`

set a goal for the precision of the path variation and the  
Euclidean action

Output is a bundled container that can be easily accessed

"Action"

sets the Eucludian spacetime dimension, 3 or 4

"Bounce"

number of field points defines the segmentation

"Coefficients"

one can pre-calculate the gradient, or make it numerical

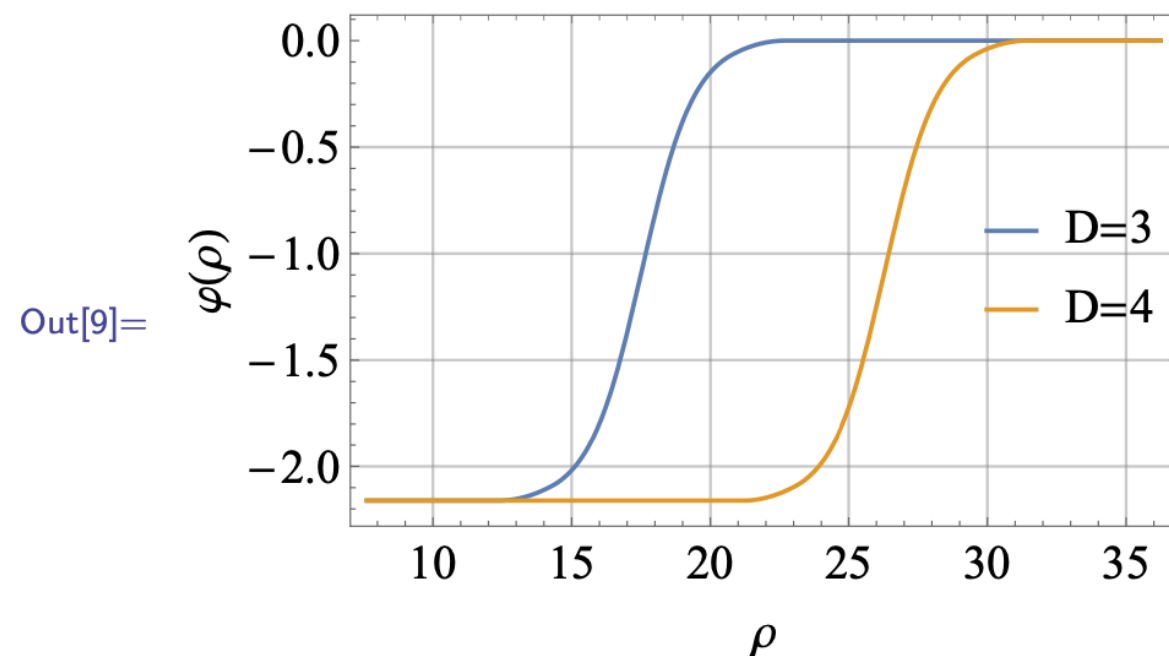
"Path"

similar to the gradient, needed for multi-fields

"Radii"

limits the number of path iterations, typically small

```
In[9]:= BouncePlot[{bf3,bf}, PlotLegends-> Placed[{"D=3","D=4"}, {Right,Center}]]
```



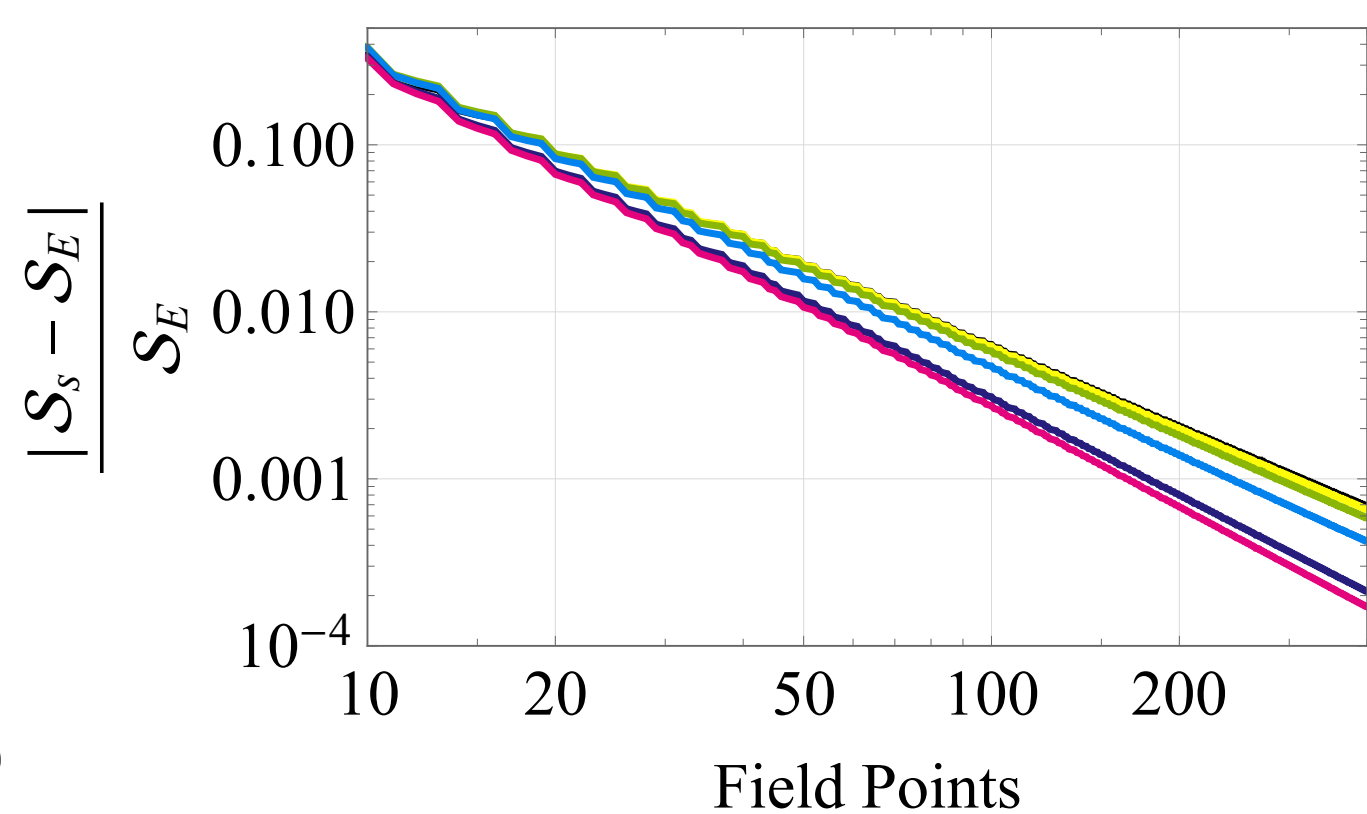
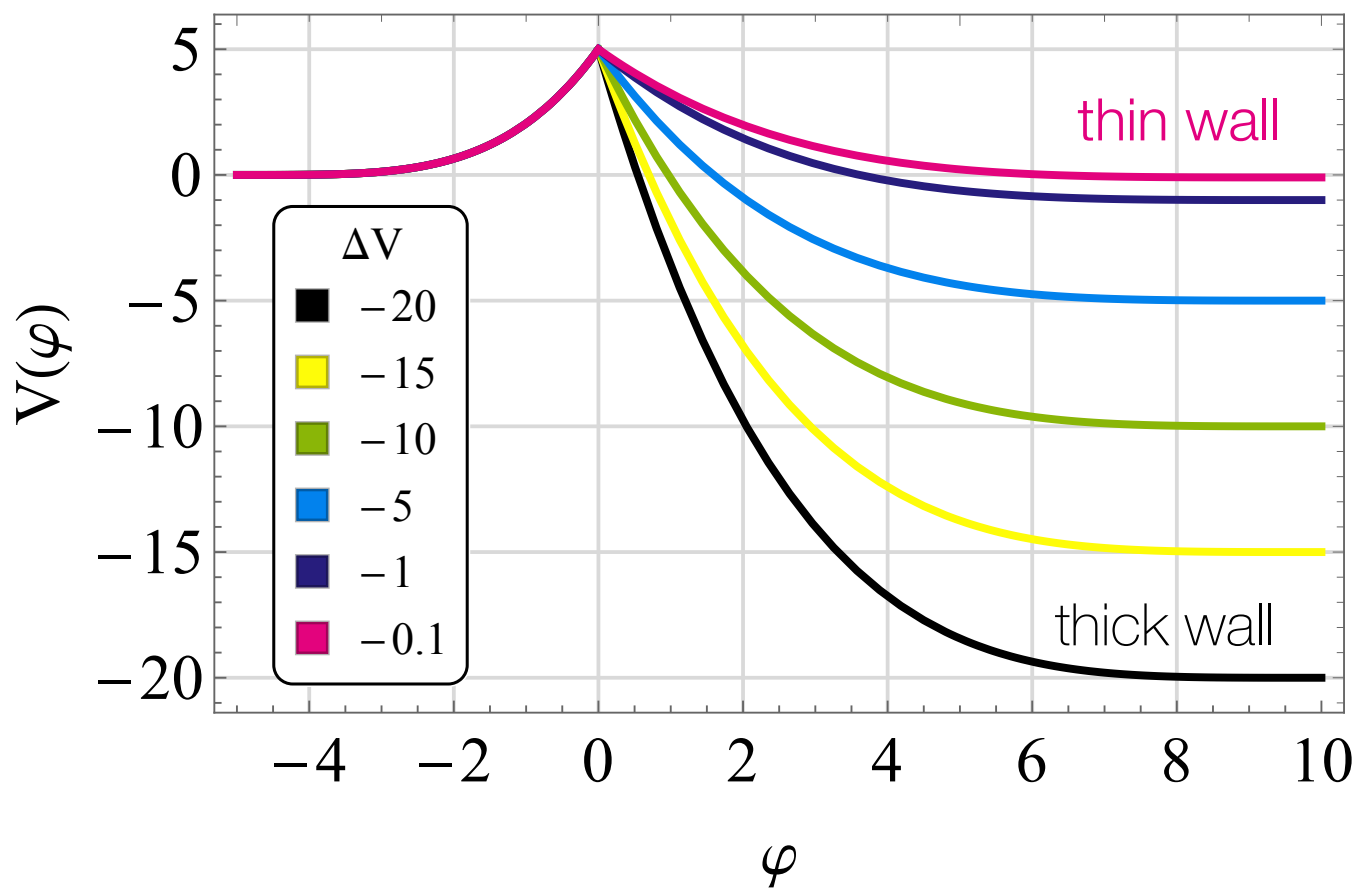
custom function for convenient plotting

# Bi-quartic

Other exact  $N=3$  potentials, quartic-linear, quartic-quartic

Dutta, Hector, Vaudrevange, Westphal '11

known exact solution, 'fair' comparison and test for the PB method



● CosmoTransitions

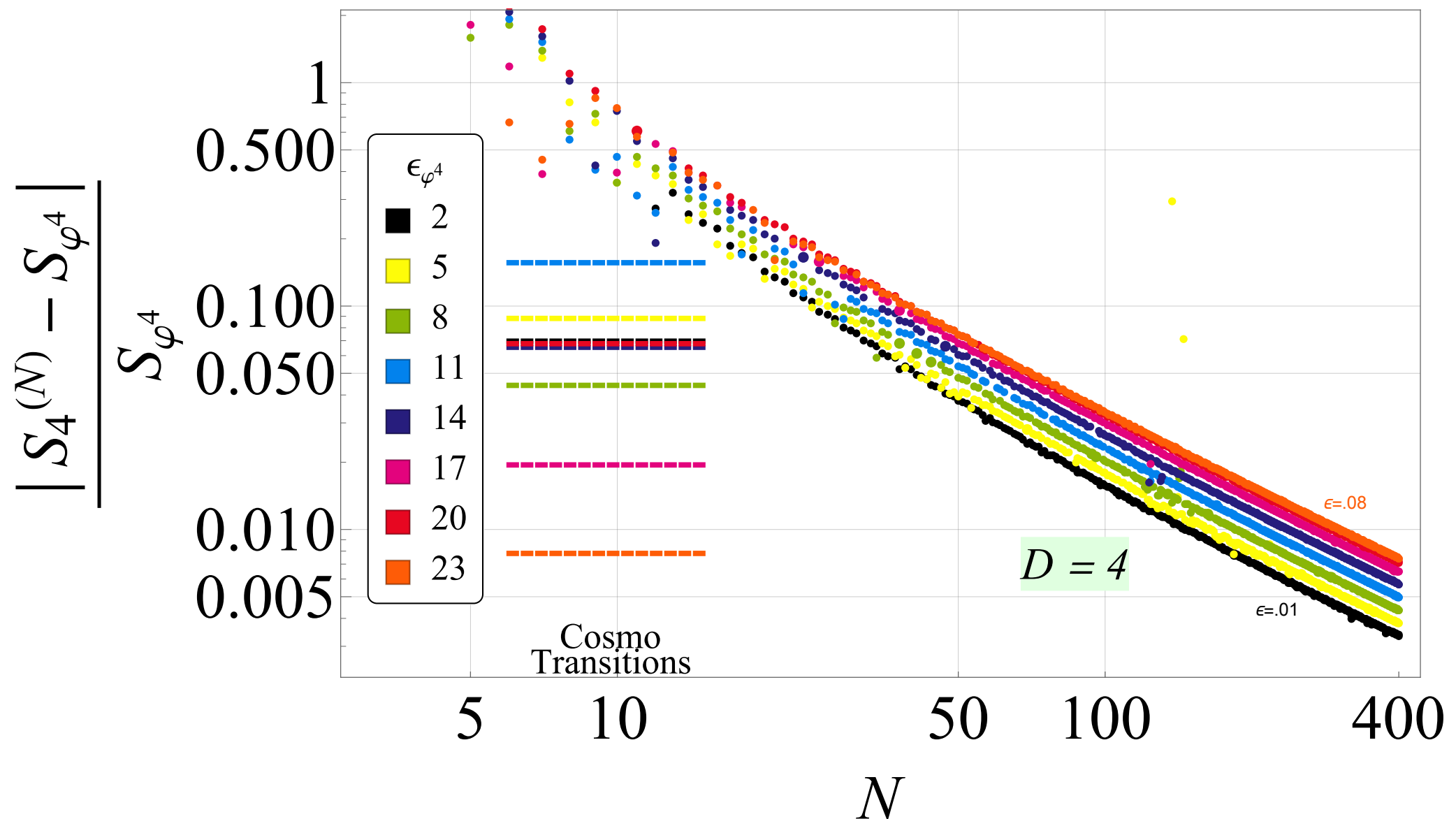
fails with the action, possible to repair by hand,  
precise from 20% to 0.5%

● AnyBubble

fails to compute

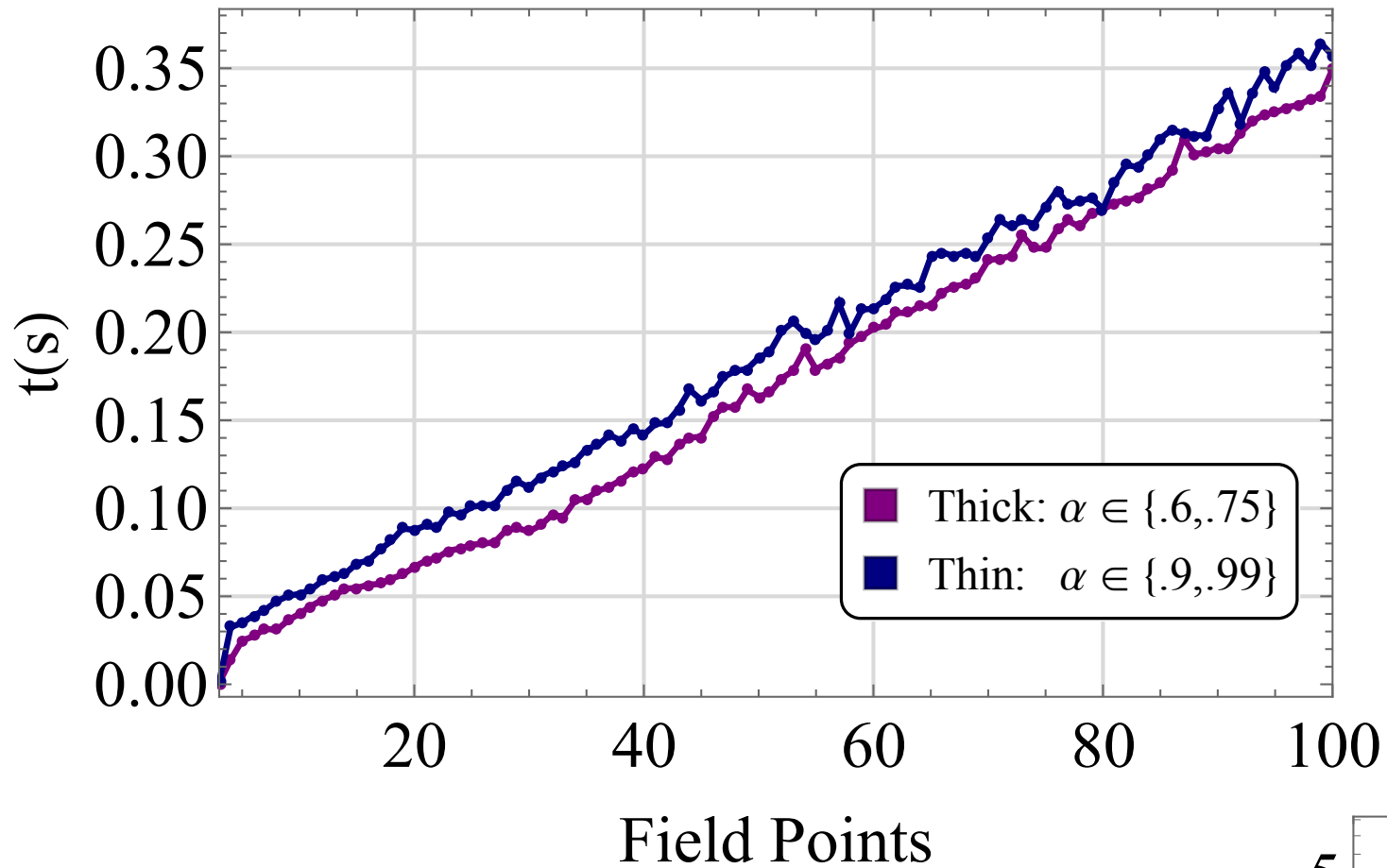
● Polygonal bounce

works smoothly with a bi-homogeneous  
segmentation





# Time demand



Scales linearly by construction

Works in thin and thick regimes

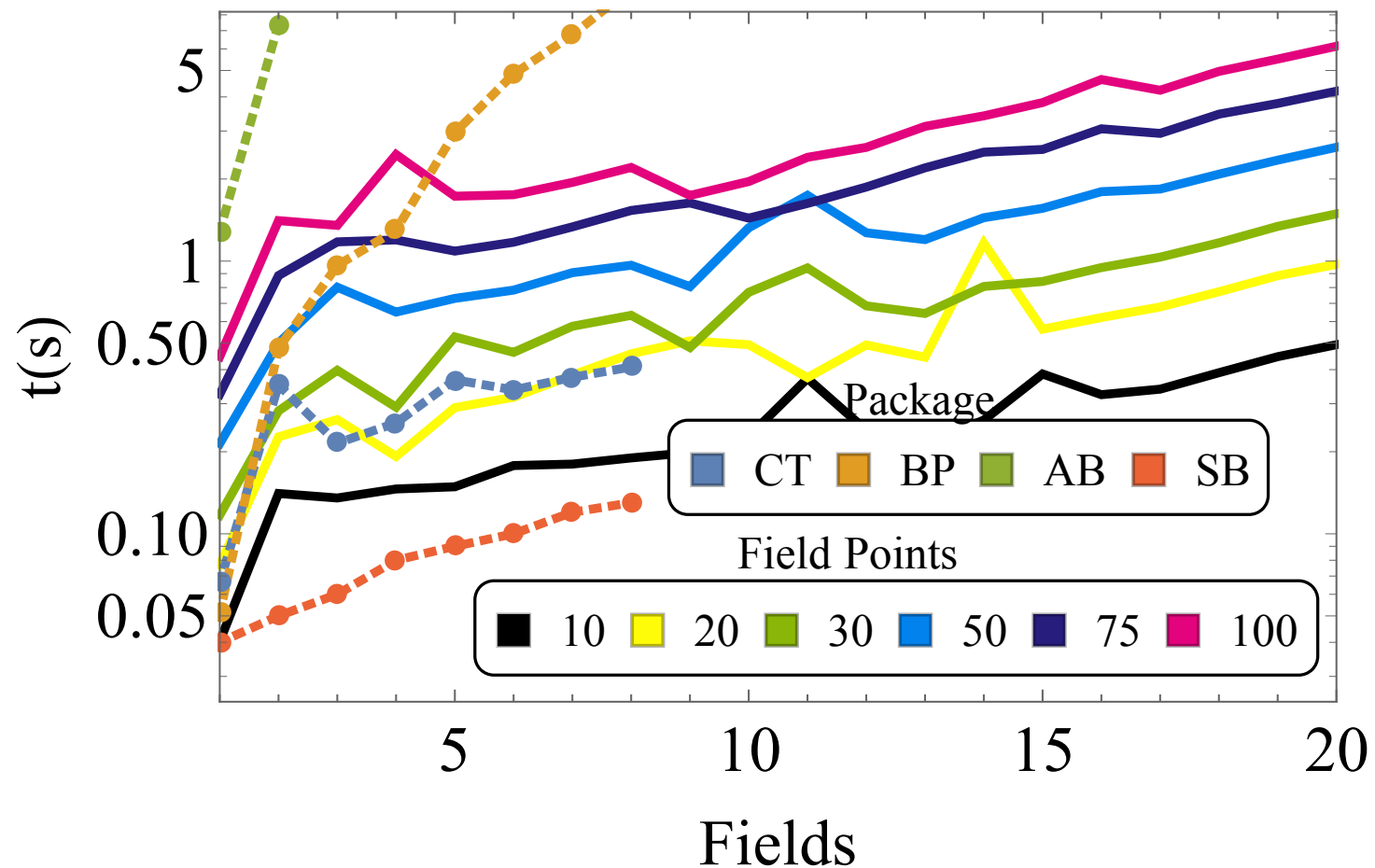
Tested up to 20 fields

CT - CosmoTransitions      Wainwright '11

BP - BubbleProfiler      Masoumi et al. '16

AB - AnyBubble      Athron et al. '19

SB - SimpleBounce      Sato '20



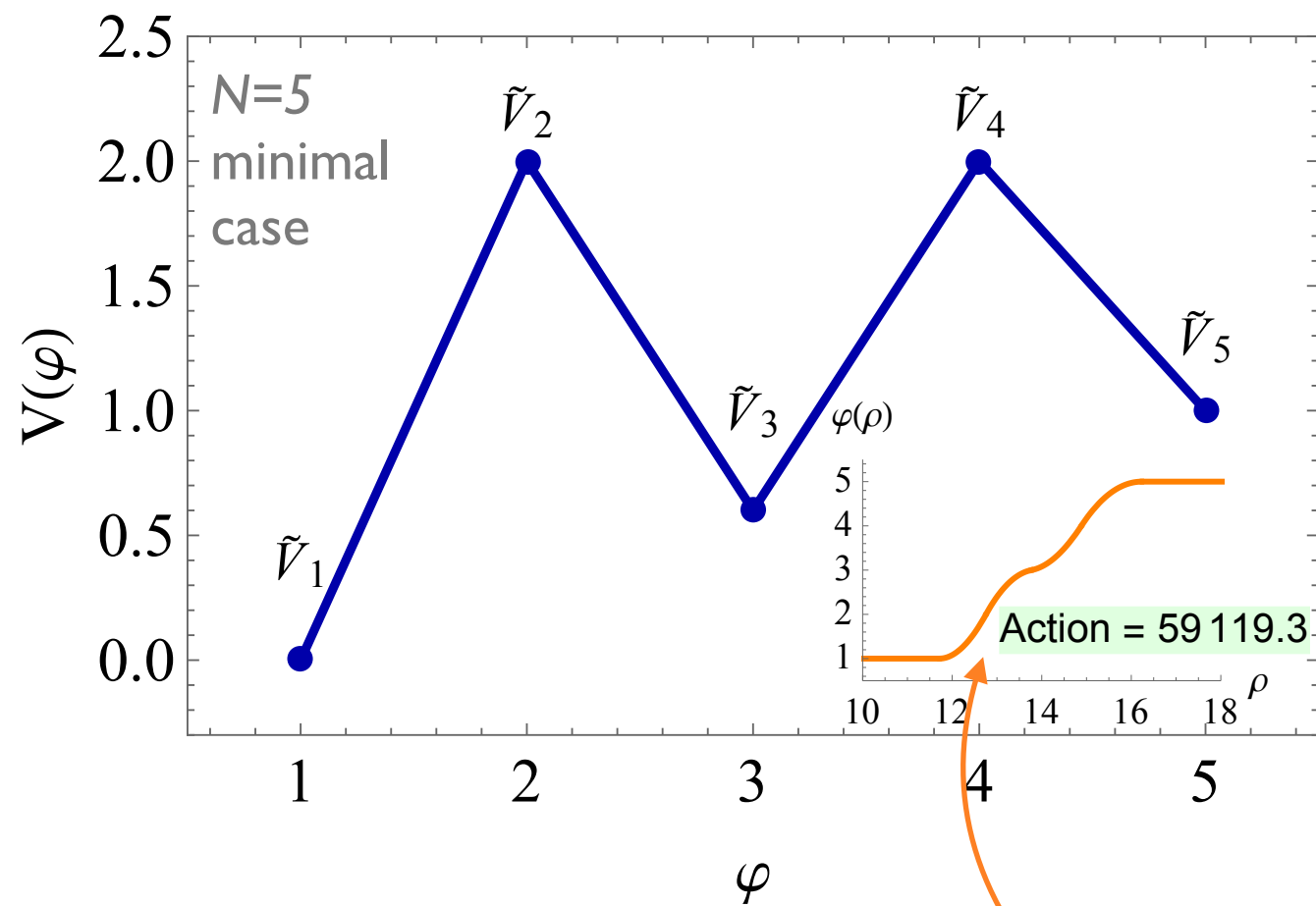
# Disappearing instanton

Intermediate minima, multi-step transitions

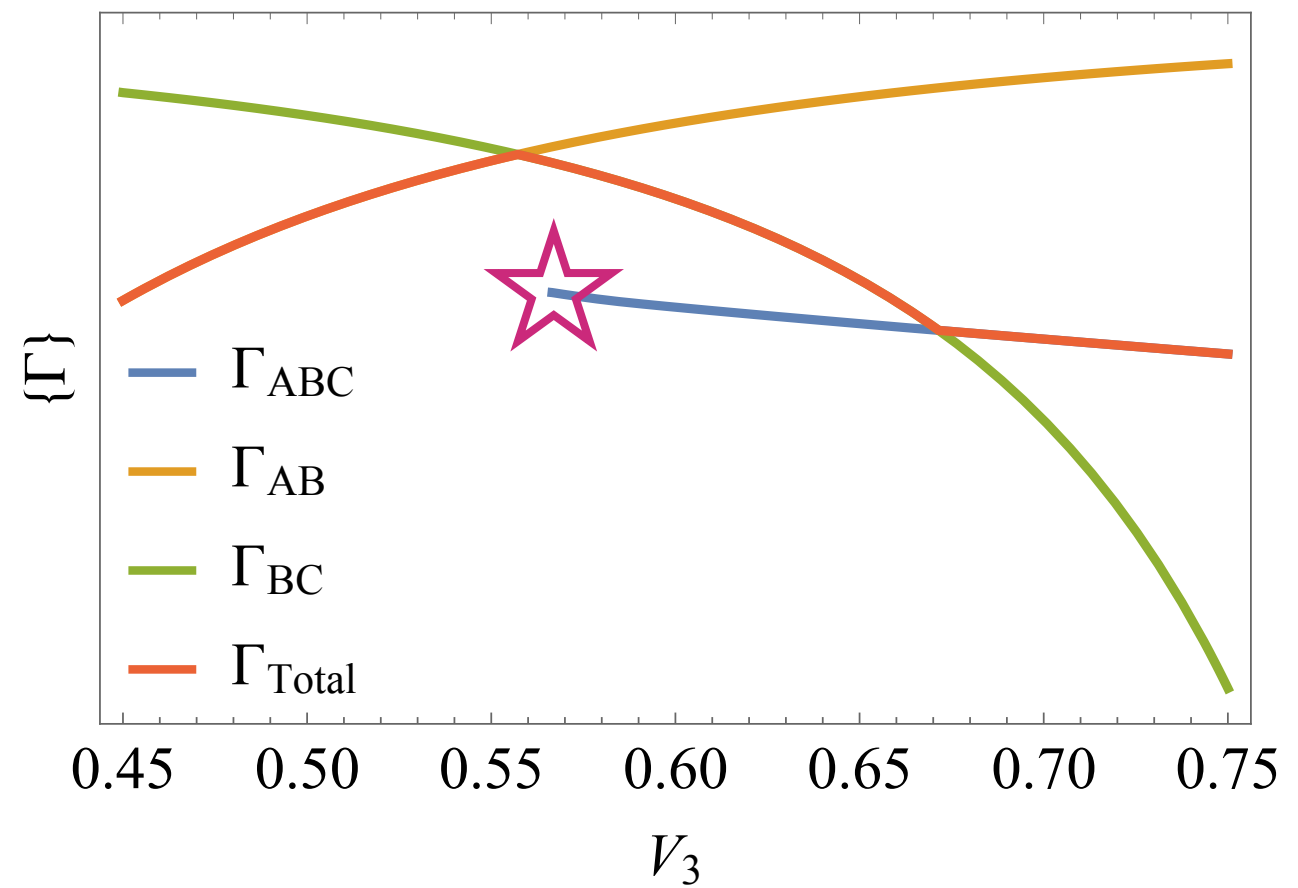
Dahlen, Brown '11

appear in theories with many fields, relaxion-type potentials

Q: which transition wins, direct tunneling or two subsequent transitions?



bubble with two  
walls



Direct tunneling impossible  
when intermediate minimum  
too low

Phase Transitions and  
False Vacua are  
fascinating and timely

Overview

Timetable

Registration

Important Information

Contact

✉ [andreas.ekstedt@physi...](mailto:andreas.ekstedt@physi...)

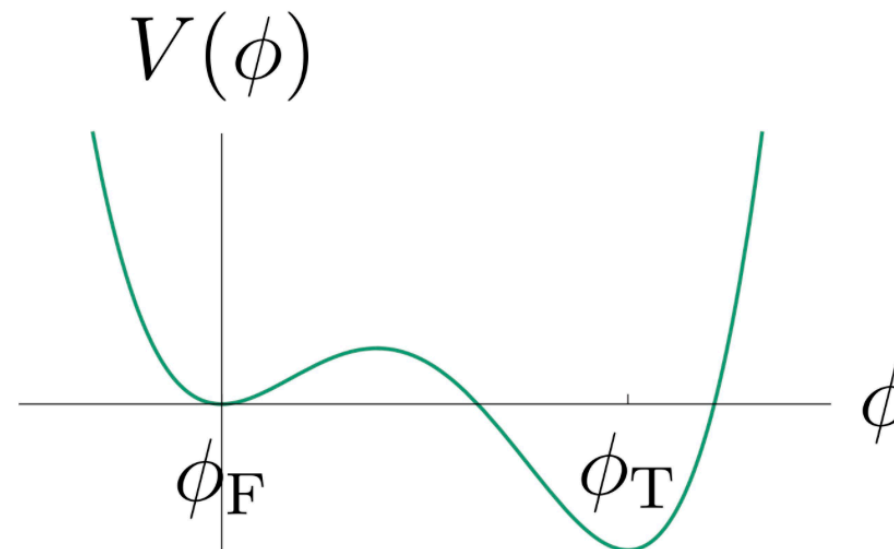
✉ [oliver.gould@nottingha...](mailto:oliver.gould@nottingha...)

✉ [miha.nemevsek@ijs.si](mailto:miha.nemevsek@ijs.si)

## Seminar series devoted to tunneling in QFT

Monthly on Thursdays, usually @ 14:00 for Central Europe (CEST in European summer and CET in winter)

Whether it be vacuum stability, phase transitions, or analogue quantum systems, tunneling is part and parcel of quantum field theory. In this seminar series we explore new developments in our understanding of these phenomena.



Indico: <https://indico.global/event/5685>

Please register on this Indico page to receive Zoom joining instructions plus a reminder for each talk.

Youtube: <https://www.youtube.com/@TunnelingQFT>